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PRELIMINARY ESTIMATES OF FREQUENCY-DIRECTION SPECTRA DERIVED FROM THE SAMSON PRESSURE GAGE ARRAY NOVEMBER 1990 TO MAY 1991

by

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ABSTRACT

In the course of the SAMSON (Sources of Ambient Micro-Seismic Noise)

Experiment conducted by researchers from Scripps Institution of Oceanography at the Coastal Engineering Research Center (CERC) Field Research Facility (FRF) near Duck, NC, a two-dimensional array of 24 bottom-mounted pressure sensors was deployed near the 13-m depth contour to detect the mattenuated pressure signal arising from the interaction of directionally opposed wave trains.

The geometry of the array was ideal for wind wave directional spectral estimation in the 0.05 to 0.24 Hz frequency band. The formal SAMSON experiment took place in October and early November 1990, but data collection continued until June 1991. Data from this post-experiment period were made available to CERC and were subsequently processed with a 360-degree Maximum Likelihood Estimation algorithm to determine the general character of the local wave field, including specifically any indications of significant seaward-propagating wind wave energy.

This report contains a description of the SAMSON array, the type of data collected, and the analysis algorithm. It contains displays, both graphic and tabular, of relevant wind wave parameters deduced from the analysis. A means of acquiring the processed data, available to the general public after June 1994, is also described.

Key Words: Frequency-direction spectra
Maximum Likelihood Estimation

Wave climate Wind waves

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Preface

This paper provides a summary of a series of wind-wave frequency-direction spectral observations made with a two-dimensional, high-resolution directional wave gage of opportunity, being the result of data shared by researchers from Scripps Institution of Oceanography (SIO) in execution of the SAMSON experiment. The work was motivated by an opportunity to conduct a 360-degree analysis of data from a 24-gage array and thus find an extraordinary observation set of directionally distributed wave energy to augment understanding and modeling of nearshore processes which affect coastal engineering projects. This effort was authorized by Headquarters, US Army Corps of Engineers (HQUSACE), under Civil Works Research Work Unit 32484, Directionality of Waves in Shallow Water, Coastal Flooding Program. Funds were provided through the Coastal Engineering Research Center (CERC), US Army Engineer Waterways Experiment Station (WES), under the program management of Mr. Charles C. Galhoun, CERC. Messrs. John H. Lockhart, Jr.; John G. Housley; Robert H. Campbell; and James E. Crews were HQUSACE Technical Monitors.

This data summary was prepared by Dr. Charles E. Long at CERC's Field Research Facility (FRF) in Duck, NC, under the direct supervision of Mr. William A. Birkemeier, Chief, FRF, and Mr. Thomas W. Richardson, Chief, Engineering Development Division, CERC; and under the general supervision of Dr. James R. Houston and Mr. Charles C. Calhoun, Jr., Chief and Assistant Chief, CERC, respectively.

The SAMSON experiment, including the directional array, was planned and executed by Drs. Robert T. Guza and Thomas H. C. Herbers of SIO. Data processing software was written by Dr. Joan M. Oltman-Shay of Quest Integrated, Inc., Seattle, WA. The concept of continued data collection after the primary SAMSON experiment is credited to Dr. C. Linwood Vincent, CERC. This document was edited by Ms. Lee Byrne, Information Technology Laboratory. WES.

Commander and Director of WES during the publication of this report was COL Larry B. Fulton, EN. Dr. Robert W. Whalin was Technical Director.

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PRELIMINARY ESTIMATES OF FREQUENCY-DIRECTION SPECTRA

DEPLUED FROM THE SAMSON PRESSURE GAGE ARRAY.

X NOVEMBER 1990 TO MAY 1991

Introduction

During October and early November 1990, an experiment involving the detection of interacting wave trains was conducted at the Coastal Engineering Research Center (CERC) Field Research Facility (FRF). Known as SAMSON (Sources of Ambient Micro-Seismic Ocean Noise), the experiment was designed to detect relatively unattenuated near-bottom pressure signals arising from nonlinear interactions of wind wave trains traveling in opposing directions. These small but detectable pressure signals are believed to initiate ocean bottom seismic waves that can propagate long distances and appear frequently in seismograms worldwide. In detecting both presence of interacting wave trains and resulting pressure signals, results of the SAMSON experiment can be used to test hypotheses concerning the initiation of such seismic waves near a coast where nearshore bathymetry can act as a partial reflector of ocean wind waves and thereby induce the requisite opposing wave trains. The experiment was designed and executed under the direction of Drs. Robert T. Guza and Thomas H. C. Herbers of the Center for Coastal Studies (CCS) at Scripps Institution of Oceanography (SIO), University of California, San Diego (UCSD), with experiment site, staging area and logistical support provided by the FRF.

- 2. The primary instrument in the SAMSON experiment was a two-dimensional array of 24 bottom-mounted pressure gages located in a nominal water depth of 13 m. By design, this depth is deeper than is normally used for measurement of ocean wind waves. The idea was to let the water column act as a filter for pressure signals arising directly from wind waves above a certain cut-off frequency. In that way, any detectable pressure signal above the cut-off frequency could be interpreted as being from the wave-wave interactions sought in the experiment. At frequencies below the cut-off, the pressure gages could readily detect wind wave signals. As a result, the array of gages was an excellent directional detector for waves in the lower part of the wind wave frequency band, from about 0.05 to 0.24 Hz.
- 3. The SAMSON pressure gage array was deployed in September 1990 and the formal experiment took place in October and early November. Scheduling

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recovery of the gages immediately after the experiment was deemed unwise because of the onset of winter and the high likelihood of poor working conditions. Hence, the gages were left in place until the following spring and, because it was a fully functioning instrument set, data were collected for as long as the gages continued to function, though this was not expected to be for very long given the harshness of the environment, in which they were deployed. Guriously, 22 of the 24 gages continued to function perfectly until the first part of June 1991, at which time the gages were recovered. Data from this post-experiment phase of instrument deployment, mid-November 1990 to the end of May 1991, have been made available to the FRF for directional analysis. This report addresses the nature and results of that analysis.

- 4. Because of the volume of data involved, considerable time has been saved by performing a preliminary, fairly rudimentary analysis to obtain the general character of the observed directional energy distributions, as described by a few simple parameters. More detailed analysis can be performed at a later date on individual cases or sequences of cases that are of most interest. The high-resolution directional estimation algorithm known as Maximum Likelihood Estimation (MLE) (Davis and Regier, 1977) is used here for the preliminary analysis because it is rather quick to compute and is adequate to describe the general directional nature of the observations. A more refined but more time-consuming algorithm, such as Iterative Maximum Likelihood Estimation (IMLE) (Pawka, 1983), can be used later to increase resolution on select cases.
- energy propagating in any direction. This allows estimation of energy propagating seaward and avoids the 180-degree ambiguity present in analysis of data from the FRF linear array directional wave gage reported previously (Long and Oltman-Shay 1991, Long 1991a, 1991b). In this report, seaward propagating energy is called "reflected" energy because reflections of incident waves from nearshore bathymetry is its most likely cause, though other processes may possibly be present. Determination of reflected directional spectra is of enormous interest in coastal research because of myriad processes that are possible theoretically if significant reflection is present. Hence, this report is the first to describe a well-resolved estimation of the full 360-degree wave climate at the FRF.

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6. The beginning text of this document describes and clarifies the substantial information contained in the appendices. A brief overview is given of the measurement site, instrumentation, data collection, and method of directional spectral estimation. These subjects are described in other publications to which the reader is referred for greater detail. Following the overview is a description of the archived frequency-direction spectra and some characterizing bulk parameters that can be derived from them. Appendix A is a listing of these characterizing parameters and is intended to be used as a kind of these characterizing parameters and is intended to be used as a kind of these parameters as a pictorial augmentation of the information in Appendix A. Appendix C is a derivation of the MLE used in this analysis. It is intended to augment the somewhat brief derivations normally found in the literature, and thereby perhaps augment the reader's understanding of this method of directional estimation.

Measurement Site

- 7. As shown in Figure 1, the FRF is located on the barrier island chain of coastal North Carolina. A detailed description of the layout, function, and capabilities of the FRF is given by Birkemeier et al. (1985). A detailed, quantitative description of the climate at the FRF, as determined from its arsenal of instrumentation and for the ten years of its existence, is given by Leffler et al. (1990). Of particular relevance to directional wave studies are the wave-steering bathymetry and wave-generating winds.
- 8. As regards the former, the coastline in the vicinity of the FRF is nearly straight for several tens of kilometers north and south (Figure 1). It is oriented such that a shore-normal line (directed seaward) is very nearly 70 deg from true north. Waves and onshore winds can approach this site along an easterly 180-deg arc from 340 to 160 deg true. The adjacent continental shelf is wide, relatively shallow, and of somewhat complex bathymetry. The direction of nearest approach of the 100-m isobath, which indicates the shelf break, is 10 to 15 deg south of east and is about 80 km distant. A typical bottom slope for the shelf is 1 m/km, but this is interrupted by numerous features of 1- to 10-km horizontal scales and 10-m vertical scales scattered irregularly across the shelf.

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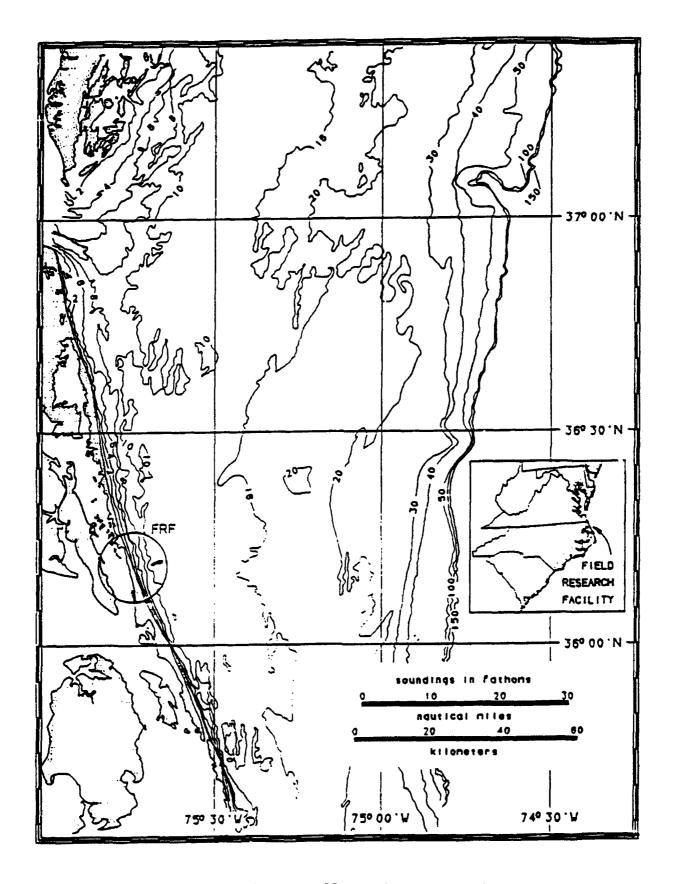


Figure 1. Location and offshore bathymetry of the FRF

- 9. Within a few kilometers of the FRF, the offshore bathymetry is more regular, with isobaths nearly shore-parallel and a bottom slope of about 2 m/km (Figure 2). Some irregularities exist. Within about 300 m of the shore, there exists a complex and mobile bar system (Birkemeier 1984). Waves and currents have created some irregular bathymetry in the vicinity of the FRF research pier which extends about 600 m offshore (Miller, Birkemeier, and DeWall 1983).
- 10. The site is subject to a variety of climates which gives rise to a diverse set of directional wave conditions. Primary sources of high-energy waves are winds associated with hurricanes and frontal passages. Though Hurricane Lily moved up the middle Atlantic Ocean during the formal SAMSON experiment, no other hurricanes affected the FRF wave climate in the period covered by this report. Low-pressure weather fronts, of which several crossed

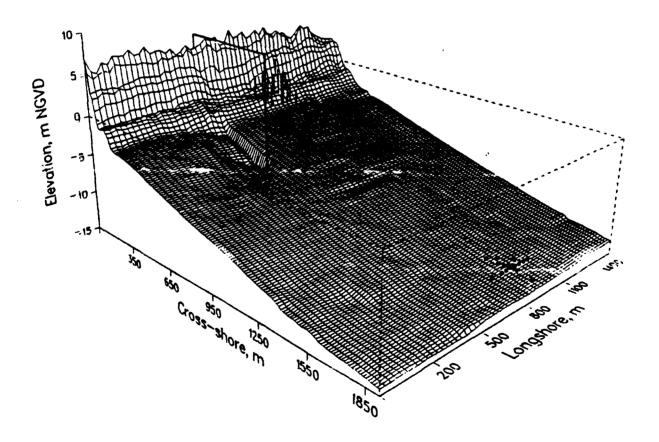


Figure 2. Approximate nearshore bathymetry and SAMSON array location (seawardmost set of dots)

the FRF site during this reporting period, were typically oriented northeastsouthwest, with strong wave-generating winds coming from the northeast.

11. As a consequence of the complex offshore bathymetry and the close proximity of wave-generating wind systems, it is expected that directional wave spectra will exhibit a rather broad, complex structure. This expectation has been realized in studies at the FRF using a linear array directional wave gage in 8 m water depth (Long and Oltman-Shay, 1991). Excepting well-sorted waves from distant storms and waves in the initial growth stages under strong steady local winds, most directional spectra were found to be rather broad. Because of the 180-degree ambiguity inherent in a linear array, it is possible that part of this broadness could be due to reflected wave energy, which is folded over to appear as incident wave energy in the linear array data processing algorithm. The ability to perform a 360-degree wave analysis with the SAMSON array will help to ascertain the extent of the error induced by the 180-degree ambiguity of the linear array, in addition to estimating the amount of seaward propagating energy.

Instrumentation

12. The primary instrument in this study was a high-resolution, two-dimensional array directional wave gage. It consisted of two parts. The first was an array of sensors that sampled sea-surface displacement at several points in (horizontal) space. The second, described in the following section on data processing and in Appendix C, is the mathematical treatment of these data to obtain estimates of wave directionality.

Basic array

below the bottom in the vicinity of the 13-m isobath about 1700 m offshore and slightly to the north of the research pier. This is shown in Figure 2 as the seawardmost set of dots. In addition to the design requirements mentioned above. Its location satisfies three constraints. First, it is generally outside the surf zone so that linear wave theory is applicable in data processing. Second, it is in water shallow enough that signals from 4-sec waves are detectable above background noise at the bottom-mounted gages. Third, it is away from the irregular isobaths around the pier and in the

nearshore bar system, which helps minimize bathymetrically induced inhomogeneities in the wave field.

14. Figure J is an enlarged view of the array layout and shows gage spacing as well as the gage numbering scheme. Spacing between the gages in the array corresponds reasonably well to the array-design criterion posed by Davis and Regier (1977) that every gage pair have a unique separation or patial lag. There are a large number of redundant lags built into the array so that multiple estimates of cross-spectral densities can be made to check

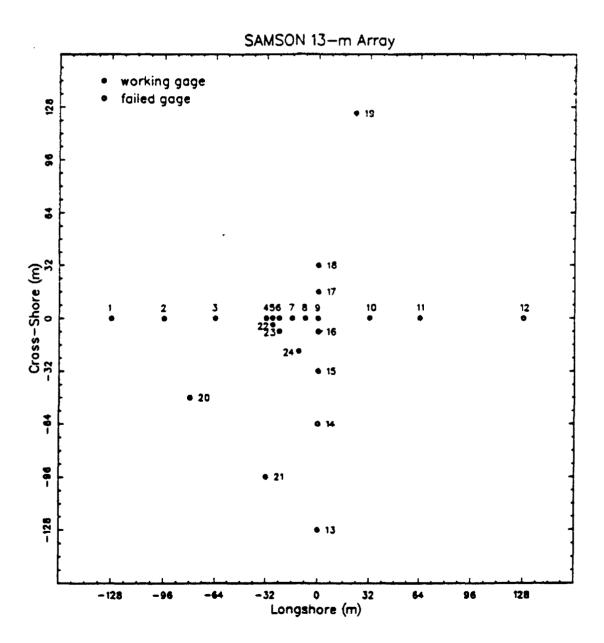


Figure 3. Layout and numbering scheme for SAMSON array

for spatial inhomogeneity in the wave field and to reduce system noise. There are a much greater number of unique lags with which to fill in the spatial cross-spectral matrix from which wave direction estimates are made. Minimum gage spacing is 4 m, maximum spacing (the greatest dimension of the array) is 256 m, and intermediate gage spacings are in multiples of 4 m. Unfortunately, gages 12 and 14 were inoperative, and the loss of gage 12 reduced the longshore dimension of the array to 192 m, at some cost to direction resolving ability for the longest (0.05 Hz) waves measured. It is noted that gage 19 appears to be offline from the basic gage pattern, and it was, in fact, slightly misplaced. However, this does not make it ineffective. In MLE processing, it is only necessary for the true gage positions to be known, and not that they conform to any particular pattern. The SAMSON gage positions were surveyed to an accuracy of better than 1 m after the gages were in place. At worst, this uncertainty would result in an error of about 1.8 degrees for the shortest (0.24 Hz) waves considered and about 0.6 deg for the longest (0.05 Hz).

Sub-arrays

- 15. At sufficiently large lags, signals from a natural wave field tend to become uncorrelated. As a result, cross-spectra between widely spaced gages tend to become mostly noise. At very small lags, correlations and cross-spectra are difficult to discern from those at zero lag and so tend to become somewhat redundant. The terms large and small are generally related to the wavelengths of waves under consideration. To avoid both redundancy at small lags and the problem of noise at large lags, the SAMSON array data were processed by using subsets of gages, or sub-arrays, based on ranges of wavelengths being considered.
- 16. Figure 4 illustrates the sub-arrays and the ranges of wave frequency used with each sub-array used in the present analysis. Note that gages 12 and 14, from which reliable data were not obtained, are not shown. For the longest waves, all the working gages were used except those which introduced the shortest (4-m) lags, i.e., gages 5 and 22. This left 20 gages for processing data in the frequency f range 0.05 < f (Hz) < 0.10 or wavelength λ range $103 < \lambda$ (m) < 220 (assuming a nominal water depth of 13 m), and included the longest possible lags.
- 17. For shorter wavelengths, the selection criterion was that the longest dimension of the sub-array not exceed about three wavelengths of the

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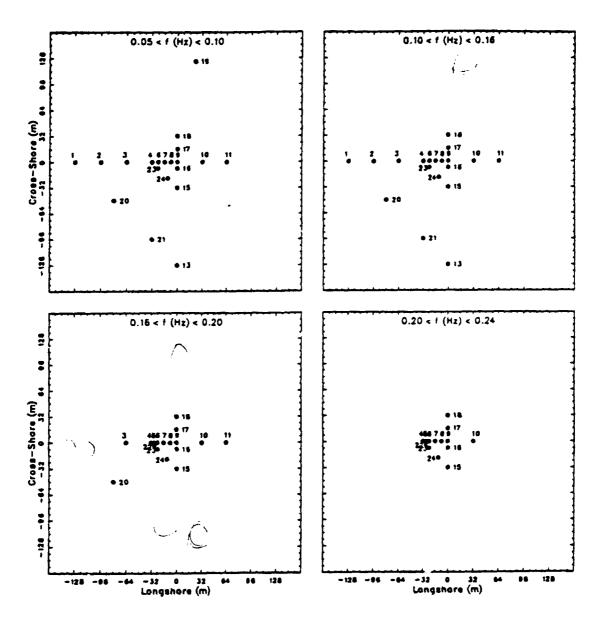


Figure 4. Sub-arrays and their associated frequency bands

shortest waves in a given band. For the low mid-range of frequencies, 0.10 < f (Hz) < 0.16, corresponding to wavelengths $55 < \lambda$ (m) < 103, this procedure eliminated gage 19 from analysis, leaving 19 gages in the sub-array. For the high mid-range of frequencies 0.16 < f (Hz) < 0.20, or $38 < \lambda$ (m) < 55, gages 1, 2, 13, and 21 were eliminated, but the short-lag gages 5 and 24 were included for a total of 17 gages. For the highest frequencies, 0.20 < f (Hz) < 0.24, $27 < \lambda$ (m) < 38, gages 3, 11, and 20 were excluded from the previous set, leaving 14 gages.

Pressure gages and data collection hardware

18. Each pressure gage is a Setra Systems Model 280E capacitive-type transducer having a range of 0 to 50 psia. The manufacturer's specifications indicate an accuracy of 0.11% of full scale or the pressure equivalent of ±0.037 m of water. Analog pressure signals were collected in an underwater terminal where they were discretized to 12-bit binary form, multiplexed, and encoded for transmission down a single data line. Digitization of the signal to 12-bit binary form resulted in a discretization uncertainty of the equivalent of 0.002 m of water. At the landward end of the data line, the encoded signal was decoded and sent to a parallel port on an AST 286 personal computer for data acquisition. During the post-experiment period, data files from the personal computer were periodically transferred to the higher-capacity hard disks of the FRF VAX 11/750 computer for accumulation and eventual archiving on magnetic media.

Data Collection

- 19. Signals from each of the 24 pressure gages were sampled at 4 Hz, and stored in records of 768 samples. A total of 1,280 records or 10,240 data points were collected for each gage for an elapsed time of 2 hr 50 min 40 sec for each collection. Starting times for collections during the main SAMSON experiment were daily at 0100, 0400, 0700, 1000, 1300, 1600, 1900, and 2200 Eastern Standard Time (EST) and this pattern was continued into the post-experiment period until 1 December 1990. At that time, collection start times were set to coincide with routine FRF observations (Birkemeier et al. 1985), which occur daily at 0100, 0700, 1300, and 1900 EST. This collection pattern was maintained until the gages were disconnected for retrieval on 1 Jun 1991.
- 20. In the analysis presented here, only the first 2 hr 16 min 32 sec (eight records of 4,096 points) of data from each collection was used. This procedure resulted in data sets that coincided both in start times and duration with other permanent directional wave gages at the FRF. It also allowed consistency in processing some collections that were terminated early to allow time for file transfers from the data collection computer to the FRF VAX 11/750 hard disks.

Data Processing

21. Conversion of measured time series to estimates of frequency-direction spectra requires products of frequency spectral estimates from all the various gages in the array. For final results to be accurate, raw input data must be of exceptionally high quality so that spiky or drifty data from one gage do not contaminate products of results from the other gages. Hence, the procedure for data processing is to check the raw data for errors, estimate the frequency-direction spectrum, and then compute some bulk parameters with which to characterize results.

Error checking

- 22. Because multiple gages were deployed in an (assumed) uniform sea, certain properties of raw data from the pressure gages should be identical. A convenient method of error checking is to compute frequency spectra of the raw time series from each of the 22 functioning gages and overplot the results on a single graph. This method was used by Drs. Guza and Herbers during the main experiment and has also been incorporated for the present analysis. Because of the depth at which the SAMSON gages were deployed, very little direct wind wave signal is expected in the frequency range from about 0.3 Hz out to the Nyquist frequency of 2.0 Hz. The frequency spectrum in this frequency band should primarily indicate system noise, which should be about the same for each gage. Excessively spiky data from one gage will raise the noise level for that gage relative to the noise levels from the other gages so that its signature will be distinct in a collection of overplotted spectra. Strong drifts in the signal can appear in a variety of ways in corresponding spectra, but will generally give a distinct signal at low frequencies. In the pass band of wind wave frequencies for which directional estimates are computed (here 0.05 to 0.24 Hz), one expects the frequency spectra to be nearly identical.
- 23. Figure 5 is an example of one set of overplotted frequency spectra. Semi-logarithmic coordinates have been used and pressure gage voltages have been converted to equivalent heights of a static water column, but no other transformations have been used. As can be seen, signals in the wind wave frequency pass band are all very nearly alike, indicating that all gages are functioning reasonably well. The noise floor at high frequencies is very low relative to the wind wave signal and is nearly uniform for all gages. The

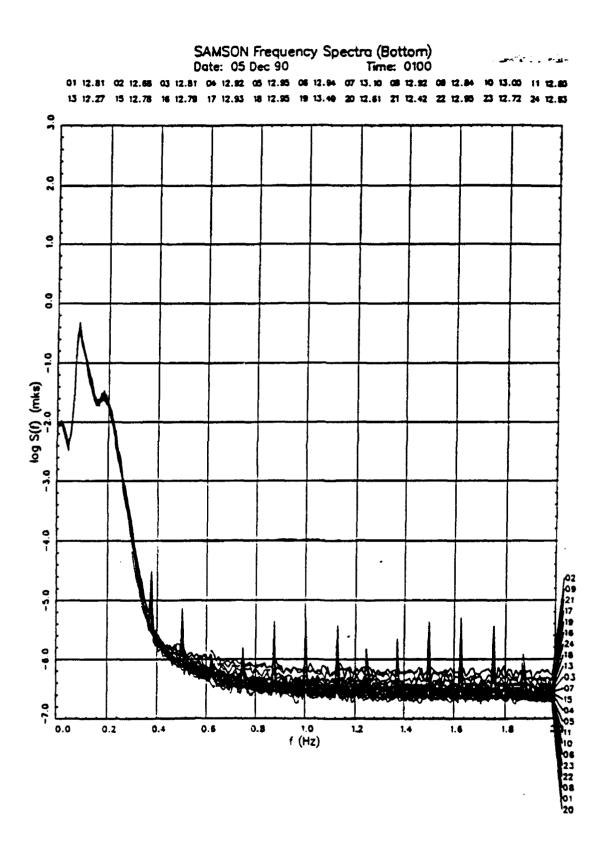


Figure 5. Example of overplotted frequency spectra

spikes in the spectra at high frequencies are due to low levels of commercial 60 Hz power line noise present in the system. The column of numbers in the right margin is the gage number associated with each spectrum. If a particular gage becomes more noisy than the others, its identifying number can then be readily determined. Because the signal mean is removed prior to spectral estimation, it would not normally appear in a spectral plot. Signal means are also useful indicators of misbehaving gages, so they are written out in the two rows of numbers below the plot header.

24. Initial tests with this kind of checking routine indicated that the SAMSON gages and data collection system were extremely reliable. Consequently, overplotted spectra were not computed for every run, but were computed for the first run of each day. At no time during the post-experiment period were any of the 22 functioning gages found to have any significant errors.

Frequency-direction spectra

- 25. Estimation of frequency-direction spectra is done in four parts. First, time series of pressure data from each gage are Fourier transformed to the frequency domain. Second, these transforms are converted to sea-surface displacement transforms. Third, cross-spectra of sea-surface displacement are computed between all unique gage pairs for each frequency. Finally, an estimate is made of a directional distribution of wave energy that corresponds to the computed spatial variation in cross-spectral density for each frequency.
- 26. The Fourier transform is conventional. A 32,768-point time series is divided into 15 half-overlapping segments of 4,096 points. Segments are tapered with a Kaiser-Bessel window (a modified Bessel function of the first kind, compensated uniformly for loss of variance due to windowing) and fast Fourier transformed. An intermediate-resolution transform is found by averaging the 15 transformed segments, frequency by frequency. Final transforms are found by then averaging results over 10 adjacent frequency bands. Final resolution bandwidth is 0.00976 Hz, and degrees of freedom are at least 150 (assuming 8 contiguous segments and ignoring any gain from lapped segments). Transform estimates are retained for 20 frequency bands with bandcenter frequency ranging from 0.054 to 0.240 Hz.
- 27. Conversion of pressure signals at depth to water-surface displacement is done through the linear wave theory pressure response factor as described in the Shore Protection Manual (SPM) (1984). After this conversion,

complex cross-spectra in the form of coincident and quadrature spectra are computed in the conventional way (Bendat and Piersol 1971, Jenkins and Watts 1968) between all unique gage pairs. Cross-spectral estimates at a given frequency are then stored in a matrix of complex numbers, the indices of which can be used to address data arrays containing gage position for the computation of gage separation distance, or lag space, in preparation for directional spectral estimation at that frequency.

- 28. In this preliminary analysis of the SAMSON data, conversion of cross-spectral patterns in lag space to directional spectra is done with the Maximum Likelihood Estimation (MLE) algorithm described by Davis and Regier (1977). The algorithm is also described in application to data from heave-pitch-roll buoys by Oltman-Shay and Guza (1984). Neither of these two references includes all the steps in the derivation, so, for pedantic completeness, a more complete outline of the derivation of MLE is given in Appendix C.
- 29. The algorithm used here made a spectral estimate for every 1 deg of azimuthal direction. These were smoothed over 2-deg arcs to create 180 bins covering a complete circle with which to describe the directional distribution of wave energy.
- 30. The primary result of data processing is an estimate of the discrete frequency-direction spectrum $S(f_n,\theta_n)$, which represents the variance of sea-surface displacement per frequency resolution bandwidth df (= 0.00976 Hz) per direction resolution arc d θ (= 2 deg), where f_n is the n^{th} of N = 20 discrete frequencies and θ_n is the m^{th} of M = 180 discrete directions. In this work, direction is considered to be the angle from which wave energy is coming, measured counterclockwise from shore normal. Also, it is pointed out that parametric definitions below are given in terms of these discrete definitions rather than in terms of the continuous functions they approximate.
- 31. Numerical values of $S(f_n, \theta_n)$ can range over many orders of magnitude, depending on the amount of energy in a given frequency band and direction arc, and this can require space-consuming formats for archiving data. To simplify this problem, frequency-direction spectra can be saved in

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^{*} For convenience, symbols and abbreviations are listed in the Notation (Appendix D).

the form of directional distribution functions $D(f_n, \ell_n)$ defined by

$$D(f_n, \theta_n) = \frac{S(f_n, \theta_n)}{S(f_n)} \tag{1}$$

where $S(f_n)$ is the frequency spectral density at frequency f_n . The directional distribution function has units of deg-1, and its integral with respect to direction over all directions is unity.

32. The frequency spectrum in Equation 1 represents the total over all directions of sea-surface variance per frequency bandwidth and is defined in terms of the frequency-direction spectrum by

$$S(f_n) = \sum_{n=1}^{N} S(f_n, \theta_n) d\theta$$
 (2)

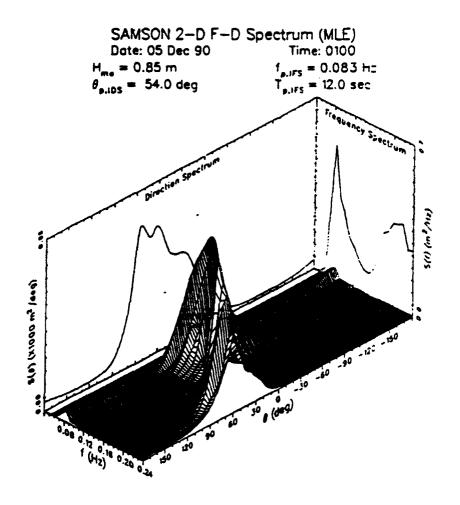
Note that this is the same thing as a conventional frequency spectrum that would result from a time series of sea-surface displacements at a single point in space. Because it is an integral of the frequency-direction spectrum, it is called the integrated frequency spectrum.

33. A directional analog of the frequency spectrum is the integrated direction spectrum, found by summing the frequency-direction spectrum over all frequencies for a fixed direction arc. It is computed from

$$S(\theta_{\mathbf{m}}) = \sum_{n=1}^{H} S(f_{n}, \theta_{\mathbf{m}}) df$$
 (3)

Figure 6 shows one way to display the frequency-direction spectrum and the corresponding integrated frequency and integrated direction spectra. Bulk parameters

- Several parameters have been computed to characterize the observed spectra. Five elementary types of parameter have been used here: water depth, characteristic wave height, peak frequency (or its inverse, peak period), peak direction, and reflection coefficient. There is more than one Trus 1> way to define some of these parameters, so definitions are presented here.
- 35. Water depth. Water depth is found from the average of the mean depths from all 22 gages in the array. It represents a water level that varies with low frequency processes like tides. Because variations in mean water level adjust intersections of the water surface with nearshore bathyare any op in? what you washed to the want of the form metry, it may be an important variable in accounting for the amount of observed reflected energy.



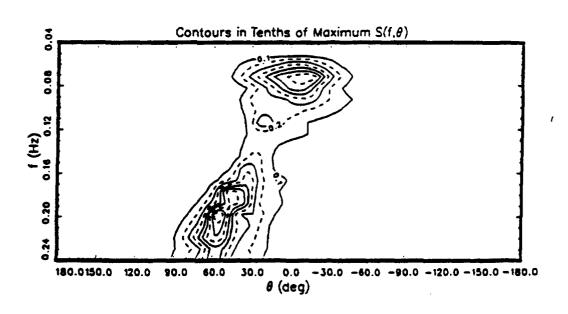


Figure 6. Sample displays of frequency spectrum, direction spectrum, and frequency-direction spectrum

36. Characteristic wave height. Characteristic wave heights from spectral observations are most frequently given as H₂₀, which is four times the standard deviation of sea-surface displacement. It can be determined from the volume under the frequency-direction spectrum by the equation

$$H_{\infty}^2 = 16 \sum_{n=1}^{N} \sum_{n=1}^{M} S(f_n, \theta_n) d\theta df$$
 (4)

It can be found equivalently from the integrated frequency spectrum by

$$H_{mo}^2 = 16 \sum_{n=1}^{N} S(f_n) df$$
 (5)

which is its conventional definition, or from the integrated direction spectrum by

$$H_{mo}^2 = 16 \sum_{m=1}^{N} S(\theta_m) d\theta$$
 (6)

37. Because the analysis yields a 360-deg distribution of wave energy, it is reasonable to distinguish between incident wave energy and outgoing wave energy, which here is arbitrarily called reflected wave energy. A characteristic incident wave height $H_{\rm mo,i}$ can be identified from the volume under the frequency-direction spectrum for waves approaching from directions in the range -90 deg $< \theta <$ 90 deg or, equivalently, the area under the integrated direction spectrum over the same range of directions. Discrete directions in the present analysis are defined by

$$\theta_{m} = 180 - 2(m - 1) \tag{7}$$

If half the energy in the 90-deg and -90-deg bins and all the energy in the intervening directional bins is attributed to incident energy, a characteristic incident wave height is

$$H_{\infty,1}^2 = \frac{1}{2}S(\theta_{46}) d\theta + \sum_{m=47}^{135} S(\theta_m) d\theta + \frac{1}{2}S(\theta_{136}) d\theta$$
 (8)

If the other half of the energy in the 90-deg and -90-deg bins and the remainder of the offshore propagating energy is attributed to reflected energy, a characteristic reflected wave height $H_{\rm mo,r}$ is given by

$$H_{mn,\pi}^2 = \sum_{m=1}^{45} S(\theta_m) d\theta + \frac{1}{2} S(\theta_{46}) d\theta + \frac{1}{2} S(\theta_{136}) d\theta + \sum_{m=137}^{180} S(\theta_m) d\theta$$
 (9)

38. Peak frequency. Peak frequency, which has the generic notation f_p , can be defined at least two ways. One way is to find the frequency (and direction) at which the frequency-direction spectrum is maximum. Another way is to find the frequency at which the integrated frequency spectrum is maximum. This is the more conventional definition and is the basic definition used here. As with characteristic wave height, a distinction is made between peak frequencies associated with incident and reflected wave energy. The peak frequency of the incident wave spectrum $f_{p,i}$ is defined as the frequency of the maximum of the integrated incident frequency spectrum $S_i(f_n)$ defined following the notation above for H_{no} as

$$S_{1}(f_{n}) = \frac{1}{2}S(f_{n},\theta_{46}) d\theta + \sum_{m=47}^{135} S(f_{n},\theta_{m}) d\theta + \frac{1}{2}S(f_{n},\theta_{136}) d\theta$$
 (10)

In a similar manner, the peak frequency of the reflected wave spectrum $f_{p,r}$ is defined as the frequency of the maximum of the integrated reflected frequency spectrum $S_r(f_n)$ given by

$$S_{r}(f_{n}) = \sum_{n=1}^{45} S(f_{n}, \theta_{n}) d\theta + \frac{1}{2} S(f_{n}, \theta_{46}) d\theta + \frac{1}{2} S(f_{n}, \theta_{136}) + \sum_{n=137}^{180} S(f_{n}, \theta_{n}) d\theta$$
 (11)

The distinction between $f_{p,i}$ and $f_{p,r}$ may be important. Unless there are very strong reflections, the incident peak frequency is virtually the same as the peak frequency one would obtain from a time series at a single point in space. If the beach is uniformly reflective (the same for all frequencies), reflected peak frequency will be the same as incident peak frequency. If the two frequencies are not equal, the beach may be significantly more reflective for certain frequencies other than the peak, a situation of no small dynamic importance in nearshore processes.

- 39. <u>Peak period</u>. Peak period T_p is the characteristic wave period associated with spectral peak frequency. As simply inverses of peak frequencies, there are two peak periods associated with a directional spectrum corresponding to the two peak frequencies defined above. The incident peak period is $T_{p,i} = 1/f_{p,i}$ and the reflected peak period is $T_{p,x} = 1/f_{p,x}$.
- 40. Peak direction. Peak direction is the direction at which the most energy occurs. Given the generic symbol θ_p , it is defined analogously to

peak frequency through the integrated direction spectrum. As with the other parameters there is an incident peak direction $\theta_{p,i}$ and a reflected peak direction $\theta_{p,r}$. Incident peak direction is the direction of the maximum of the integrated incident direction spectrum, which is Equation 3 restricted to those directions for which -90 deg $< \theta < 90$ deg or for which index m is in the range 46 < m < 136 . Reflected peak direction is the maximum of the integrated reflected direction spectrum, again Equation 3 but now restricted to offshore propagation directions. This restriction leads to two ranges (in the present definition) of direction -180 deg $< \theta <$ -90 deg and 90 deg $< \theta$ < 180 deg or of direction indices 1 < m < 46 and 136 < m < 180 . These measures of peak direction indicate only the single direction cells in each direction range that contain the most energy. If much depth- and frequencydependent refraction is occurring (as appears to be occurring in Figure 6. e.g.), the integrated direction spectra are somewhat smeared across the direction axis. Feak directions thus found may not correspond then with any peaks in the full frequency-direction spectrum. Hence, these parameters, while adequate for preliminary analysis, must be considered as very rough characterizations.

41. Reflection coefficient. Following notation and definitions given in SPM, reflection coefficients χ are generally defined as ratios of reflected to incident wave heights. Coefficients indicating ratios of energy would then vary as the squares of height-based coefficients defined here. Three reflection coefficients are identified. The first is a bulk parameter that characterizes total reflected to total incident energy. These two energies are the volumes under the reflected and incident spectra, respectively, and are the sources of the definitions of $H_{mo,r}$ and $H_{mo,t}$, respectively. Because it is a wave height ratio that is used in the definition, a bulk reflection coefficient χ_{max} is simply

 $x_{mo} = \frac{H_{mo.x}}{H_{mo.1}}$ $= \frac{H_{mo.x}}{H_{mo.1}}$ $= \frac{H_{mo.x}}{H_{mo.1}}$ $= \frac{H_{mo.x}}{H_{mo.1}}$ $= \frac{H_{mo.x}}{H_{mo.1}}$ $= \frac{H_{mo.x}}{H_{mo.x}}$ $= \frac{H_{mo$ The other two reflection coefficients are frequency specific. One is based on the square root of the ratio of reflected to incident energy at the peak frequency of the incident spectrum and suggests how much of the energy at the frequency spectral peak is reflected. Denoted $\chi_{p,1}$, it is defined from the incident and reflected frequency spectra given by Equations 10 and 11,

respectively, as

$$\chi_{p,i} = \left[\frac{S_r(f_{p,i})}{S_i(f_{p,i})} \right]^{\frac{1}{2}}$$
 (13)

Because the peak in the reflected energy may not occur at the peak frequency of the incident spectrum, a third reflection coefficient is defined from the ratio of frequency spectral energies at the peak frequency of the reflected spectrum. Denoted $\chi_{p,x}$, it is defined by

$$\chi_{p,r} = \left[\frac{S_r(f_{p,r})}{S_i(f_{p,r})}\right]^{\frac{1}{2}}$$

Together, these parameters give a bulk characterization of some properties of a frequency-direction spectrum. There are, of course, many 20 p. and AzB other parameters that can be defined, but the present set is simple and is adequate for this preliminary analysis.

Archived Results

need to reliability have
discuss in voir etc have 43. A magnetic tape containing the set of observed frequency-direction spectra has been prepared for copying and distribution. These spectra are immediately available to researchers within the USACE and are available to the general public after June 1994. They can be obtained by communicating with:

> Chief, Field Research Facility 1261 Duck Road Kitty Hawk, NC 27949-4471 Phone: (919) 261-3511 Fax: (919) 261-4432

- 44. Appendix A contains a listing of the date, starting time, and the characterizing parameters defined previously for each case. It is intended to be used as a kind of index or catalog of the set of cases. Dates are given in the form yymmdd where yy is a two-digit year indicator (e.g., 90 means 1990), mm is the numeric index of the calendar month (i.e, 01 is January, 12 is December, etc.), and dd is day of the month. All times are Eastern Standard Time. A 24-hr clock is used.
- 45. Some of the bulk parameters defined above are plotted as functions of time in Appendix B. One graph is shown for each month of the post-

experiment period. Shown are H_{mo} , $H_{mo,i}$, $H_{mo,r}$, depth, $\theta_{p,i}$, a modified form of $\theta_{p,r}$, $T_{p,i}$, $T_{p,r}$, χ_{mo} , $\chi_{p,i}$, and $\chi_{p,r}$. The modification to $\theta_{p,r}$ involved a shift of 180 deg so that, in the figures, this variable represents direction toward which reflected waves propagate. The variable $\theta_{p,i}$ continues to represent direction from which incident waves arrive.

Discussion

- 46. The intent of this report is to indicate that additional frequencydirection spectral observations have been added to the already extensive FRF data base and to characterize these observations with some simple parameters. There is clearly much more work to be done with this extraordinary data set, including scientific interpretation, but that is beyond the scope of this document. The descriptive parameters used here are defined simply to be preliminary indicators of the nature of the data. Close examination of the parameters displayed in Appendix B indicates that the rudimentary definitions used here may be somewhat misleading. Hence, there are a few caveatae for the reader.
- In plots of characteristic wave height, it is clear that most of the total wave energy, characterized by H , is in the incident spectrum which is characterized by H ... The so-called reflected energy, indicated by $H_{mo,x}$ is small, but is very seldom zero. It is possible that some energy always reflects from the FRF beach, but there are (at least) two other reasons for this indication of reflection that is not related to reflection at all. One reason is that there is usually some low-level, broad band background noise in the data, which the MLE algorithm tends to distribute uniformly around the horizon. Integration of the spectra with respect to direction then tends to suggest more reflected (and incident, but to a lesser extent) energy than is actually present. A second misleading indicator occurs if the tails of directional distributions for incoming waves extend beyond the arbitrarily assigned 90-deg limit for incident energy. In the definitions used here, the energy represented by these extended tails becomes associated with reflection when it is more likely part of an onshore distribution of energy where the peak is at a large, but less than 90-deg, angle to shore normal. Figure 6 Not actuell to a level fucts &

 It is just nek him the noise

 It is just haven have the noise illustrates both these effects. A low level of energy is perceived at all

23

directions in the integrated direction spectrum and high-frequency waves have a high angle of attack, with energy distribution tails that exceed 90 deg.

- 48. These effects have consequences in some of the other parameters, as well. If there is significant energy in distribution tails that cross one of the 90-deg boundaries, the search algorithm will likely find one of those tails and the corresponding 90-deg boundary as the peak energy point for the reflected spectrum. Hence, there will be a number of cases where $\theta_{p,r}$ is 90 deg or -90 deg. This is seen to be the case in the figures in Appendix B. Though not as obvious, peak reflected periods $T_{p,r}$ derived from peak reflected frequencies $f_{p,r}$ are also affected.
- 49. Finally, reflection coefficients, deduced from the integral properties of the spectra, are also somewhat biased. This is especially noticeable when low incident wave conditions exist. When the low, but persistent, background levels of the so-called reflected energies are divided by low incident wave energies, the ratio can become of order 1, which is unrealistically high.
- 50. These observations do not entirely preclude the usefulness of the parameters defined here. High energy conditions are readily identified, as are primary directions and periods. In some high energy conditions, reflected wave heights rise above the background level and suggest the existence of legitimate reflected energy. The point here is that brute parameter definition, even though reasonable at some low level of reliability, can mislead. Clearly, more elegant definitions are required for sound scientific interpretation, a task reserved for future work.

Summary

51. Data from the post-experiment period of the SAMSON project has provided an opportunity to add to the FRF data base of high-resolution, directional-spectral observations. Processed data have been put in a form that will be highly accessible to researchers interested in nearshore processes. Directional gage, directional analysis algorithms, and definitions of characterizing parameters are described. The parameters used here are crude, but adequate for case distinction in this preliminary analysis. More refined parametric definitions will be necessary for proper scientific interpretation of the data.

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Appendix A: Table of Collection Times and Bulk Parameters

Bulk Parameters of Observed Frequency-Direction Spectra

		Wave Height			Dir	ection	Tre	MISBOY	2			
Dere	71			E _{BO, T}	0p.1			£p,r		Y- 1	Xp,z	Denth
	EST				495	des	7:1	<u></u>	~	^p, 1	~9,5	
901112	1600	0.68	0.65	0.18	20.0	90.0	0.132	0.132	0.280	0.278	0.278	13.44
901112		0.66			24.0		0.152	0.171	0.262	0.192	0.346	12.85
901112	_	0.70	0.68	0.17	18.0					0.227		
		••••		••••			••••					
901113	0100	1.03	1.01	0.20	28.0	90.0	0.132	0.132	0.196	0.208	0.208	13.40
901113		1.21	1.19		24.0					0.167		
901113		1.10	1.08	0.21	26.0					0.149		
901113		1.07	1.04	0.25	30.0					0.219		
901113		0.91	0.89	0.19	34.0					0.197		
,,,,,,				****								
901114	0100	1.35	1.32	0.25	32.0	90.0	0.152	0.132	0.193	0.182	0.196	13.41
901114		1.43	1.40	0.30	42.0					0.153		
901114		1.48	1.45	0.31	28.0					0.163		
901114		1.35	1.32	0.26	28.0					0.169		
901114		1.24	1.20	0.31	26.0					0.211		
901114		1.05	1.01	0.29	18.0					0.281		
901114		0.92	0.89	0.21	18.0					0.180		
701114	2200	V.72	4.47	0.22	20.0	2.0.0					••••	
901115	0100	0.79	0.76	0.21	20.0	-170.0	0.132	0.132	0.280	0.252	0.252	13.30
901115		0.70	0.67	0.21		-164.0			-			
901115		0.57	0.54	0.18		-180.0						
901115		0.49	0.46	0.15		-178.0						
901115		0.46	0.44	0.14	12.0					0.353		
901115	-	0.42	0.40	0.13	6.0					0.344		
901115		0.34	0.32	0.12	2.0					0.317		
901115		0.32	0.30	0.12	-2.0					0.277		
A01113	2200	0.32	0.30	0.12	-2.0	170.0	V.113	0.113	V. 330	U. Z.	V. 323	
901116	0100	0.31	0.29	0.11	-1A.G	-180.0	0.132	0.113	0.198	0.249	0.459	13.04
901116		0.28	0.26			-176.0						
901116		0.25	0.23			-176.0						
901116		0.20	0.18			-176.0						
901116		0.19	0.17	0.08		-134.0						
,,,,,,	2200	4.27	•									
901117	0100	0.19	0.16	0.10	-28.0	-176.0	0.064	0.064	0.601	0.850	0.850	12.85
901117		0.20	0.17		-46.0					0.782		
901117		0.20	0.16			-132.0						
901117		0.95	0.91	0.28	58.0					0.332		
901117		1.30	1.25		50.0					0.280		
901117		1.40	1.34		42.0					0.209		
901117		1.70	1.65	0.44	38.0					0.196		
901117		2.23	2.16	0.54	30.0					0.138		
901117	2200	2.23	2.20	4.54	20.0	,,,,		0.430	٠. ڪ	4.430	0.505	
901118	0100	2.35	2.28	0.59	26.0	90.0	0.142	0.191	0.259	0.182	0 329	13.27
901118		2.28	2.18		24.0					0.246		
901118					20.0					0.293		
901118			_,		14.0					0.219		
901118		-		0.54	20.0					0.190		
901118			1.80			90.0						
901118				0.46		90.0						
										0.223		
901118	4400	1.83	1.79	U. 4V	20.0	y U . U	J. 103	J. 103	J. 223	443	J . AA3	
001110	0100	1 47	1	0.43	18 0	-174.0	0 102	0 002	0 210	0 246	0 254	11 20
901119						-174.0						
			1.75	0.44	14.0	-174.0	0.073	Q.U73	0.43/	0.232	0.232	14 77
901119			1 87	0.40	16.0	-174.0	0.043	0.074	0 303	0.233	0 117	13.21
						-176.0						
901119	TOUR	1.01	1.74	U.47	14.0	-110.U	va.i	J. JEJ	₩.441	V. 484	J. 254	

^{*} See Notation (Appendix D) for definitions of terms

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	ISI					des				^9,1	^p, r	
`		_										
901119	1900	1.48	1.41	0.42	14.0	-178.0	0.083	0.083	0.298	0.269	0.269	13.85
901119	2200	1.33	1.25	0.44	16.0	-176.0	0.083	0.083	0.354	0.364	0.364	13.61
001120						-176 0						
901120 901120		1.20	1.13	0.38		-176.0 -178.0						
901120		1.07	0.97	0.45		-168.0			_			
901120		0.93	0.88	0.32		-172.0						
901120		0.95	0.91	0.27		-174.0						
901120		0.99	0.96	0.27		-176.0						
901120	1900	1.02	0.98	0.27	24.0	-172.0	0.093	0.093	0.279	0.388	0.388	13.77
901120	2200	1.05	1.02	0.26	22.0	-176.0	0.181	0.093	0.258	3.200	0.323	13.70
901121		1.24	1.21	0.28		90.0						
901121		1.17	1.14	0.26		90.0						
901121 901121		1.14	1.11	0.26		-168.0						
901121		1.03	1.00	0.26		-174.0 -172.0						
901121		1.02	0.99			-170.0						
901121		0.88	0.84	0.23		-168.0						
901121		0.77	0.74	0.22		-170.0						
								•			- 10.0	
901122	0100	0.70	0.67	0.20	20.0	-164.0	0.103	0.113	0.292	0.308	0.351	13.25
901122	0400	0.67	0.64	0.19	14.0	-166.0	0.113	0.113	0.306	0.353	0.353	13.21
901122		0.65	0.61	0.22		-164.0						
901122		0.61	0.58	0.18		-172.0						
901122		0.56	0.53	0.18		-154.0						-
901122		0.54	0.51	0.16		-172.0						
901122 901122		0.54	0.51	0.18		-150.0 -174.0						
701122	2200	0.49	u.47	0.13	•.0	-1/4.0	0.132	0.132	0.331	U.366	v.366	13.00
901123	0100	0.47	0.44	0.16	10.0	-152.0	0.123	0.113	0.374	0.355	0.404	13.32
901123		0.48	0.45	0.16		-176.0						
901123	0700	0.51	0.47	0.19		-152.0					-	
901123	1000	0.47	0.44	0.17	10.0	-178.0	0.113	0.123	0.377	0.373	0.391	13.80
901123	1300	0.43	0.39	0.17	8.0	176.0	0.113	0.113	0.437	0.495	0.495	13.42
901123		0.42	0.38	0.18		-174.0						
901123		0.46	0.42	0.18		-156.0						
901123	2200	0.40	0.37	0.15	14.0	-176.0	0.113	0.103	0.401	0.354	0.473	13.62
901124	0100	0 34		0.13		-174.0						
901124		0.34	0.31 0.27	0.11		-178.0		-				
901124		0.28	0.25	0.12		-176.0						
901124		0.30	0.27	0.13		-172.0						
901124		0.31	0.28	0.14		-170.0						
901124	1600	0.32	0.29	0.15		-172.0						
901124	1900	0.34	0.29	0.17	20.0	-176.0	0.093	0.093	0.590	0.635	0.635	13.08
901124	2200	0.34	0.29	0.16	20.0	-172.0	0.093	0.093	0.558	0.597	0.597	13.47
901125	0100	0.30	0.28	0.13	12.0	-174.0	0.093	0.093	0.459	0.467	0.467	13.38
					16.0	-174.0	0.093	0.093	0.503	0.557	0.557	12.95
901125					4.0	-178.0	0.093	0.103	U.543	0.569	D. 686	12.97
901125					-56.0	-174.0 -172.0	0.103	0.093	U.303	U.345 (U.071 :	13.39
901124	1600	0.25	0.23	0.10	~5#.O	-90.0	0.073	0.063	0.43¥ \	0.914 (0.478 (0.040) n 474 1	13.40
901125	1900	0.26	0.24	0.11	-58.0	-90.0	0.103	0.064	0.467	0.603	0.755	12.83
901125		0.28	0.26	0.10	-56.0	-90.0	0.103	0.064	0.40A	0.462	7.741	13.31
			•-							'		
901126	0100	0.26	0.24	0.09	-54.0	-90.0	0.162	0.064	0.388	0.352	7.710	13.49
901126	9400	0.25	0.23	0.10	-56.0	~90.0	0.152	0.064	0.434	0.315 (.768 1	13.11

(Continued)

(Sheet 2 of 18)

(Continued)

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Date	Time		E.			<u> </u>	<u> </u>	₹ _{p,z}	Y	7- 1	Yp,r	Depth	
	ISI_		-0,1		des		_i	_ <u></u>			-y, r		
901126	0700	0.25	0.22	0.12	-26.0	-178.0	0.064	0.064	0.526	0.642	0.642	12.92	
901126		0.26	0.23	0.13		-172.0							
901126		0.30	0.26	0.15		-176.0							
901126		0.32	0.27	0.16		-174.0							
901126		0.33	0.27	0.18		-176.0							
901126		0.39	0.32	0.23		-172.0							
901127	0100	0.40	0.33	0.22	-6.0	-174.0	0.054	0.054	0.651	0.742	0.742	13.71	
901128	0100	0.45	0.40	0.21	6.0	-170.0	0.074	0.064	0.515	0.684	0.811	13.72	
901128	0400	0.44	0.40	0.18	2.0	-172.0	0.074	0.064	0.462	0.544	0.711	13.59	
901128	0700	0.46	0.42	0.18	14.0	-90.0	0.074	0.074	0.435	0.582	0.582	13.02	
901128		0.55	0.51	0.21	-58.0	-90.G	0.191	0.074	0.404	0.277	0.649	13.03	
901128		0.55	0.50	0.21	2.0								
901128	-	0.58	0.54	0.21	-54.0	-90.0	0.191	0.064	0.382	0.368	0.732	13.48	
901128		0.48	0.45	0.17	-52.0		_			0.431			
901128		0.47	0.43	0.19	-56.0					0.341			
901129	0100	0.54	0.51	0.18	-56.0	-90.0	0.191	0.074	0.353	0.270	0.541	13.54	
901129		0.56	0.52	0.20	-52.0	-90.0	0.191	0.074	0.384	0.348	0.404	13.69	
901129		0.52	0.49	0.18	~50.0	-90.0	0.171	0.074	0.375	0.300	0.586	13.03	
901129		1.13	1.08	0.34	52.0	90.0	0.191	0.240	0.315	0.250	0.440	12.80	
901129		1.72	1.67	0.39	38.0					0.190			
901129		1.68	1.62	0.46	36.0	90.0	0.171	0.171	0.282	0.263	0.263	13.76	
901129		1.78	1.71	0.48	34.0		-			0.262			
901129		1.96	1.90	0.50	34.0					0.184			
901130	0100	2.38	2.31	0.60	32.0	90.0	0 142	0.240	0.261	0.143	0.453	13.76	
901130		2.15	2.07	0.58	36.0					0.171			
901130		1.88	1.81	0.48	28.0					0.197			
901130		1.69	1.65	0.36	30.0					0.158			
901130		1.48	1.45	0.31	26.0					0.167			
901130		1.31	1.27	0.32	30.0					0.260			
901130		1.13	1.10	0.27	22.0					0.190			
901130		1.01	0.99	0.21	22.0					0.210			
901201	0100	0.89	0.85	0.25	24.0	-166.0	0.142	0.123	0.295	0.218	0.359	13.36	
901201		0.76		0.26		-164.0							
901201		0.64	0.59	0.23		-170.0							
901201		0.52	0.49	0.17		180.0							
901201		0.46	0.42	0.19		-176.0							
901202	0100	0.48	0.43	0.20	10.0	-178.0	0.093	0.093	D. A67	0.500	0.500	12.88	
901202		0.41	0.37	0.19		-174.0							
901202			0.36			-176.0							
901202						-170.0							
****		• • •				.174.0							
901203					2.0	-176.0	0.103	U.U53	0.44/	0.35/	0.339	14.55	
901203						-90.0							
						-90.0							
9 01203	1900	1.35	1.32	0.40	-10.0	-90.0	0.132	u.132	U.300	U.349	U.349	13.92	
901204						-90.0							
901204						-90.0							
901204						176.0							
901204	1900	0.79	0.72	0.32	10.0	-176.0	U.074	0.074	U.445	0.523	0.523	13.84	
						90.0							
901205	0700	0.87	0.84	0.24	32.0	90.0	0.162	0.113	0.293	0.224	0.523	14.04	

(Sheet 3 of 18)

_			TO He			ection.						_
	Time	E _{mo}		Emo, r	e,i	dp,r	د.2	. £2,2	X _{mo}	Xp, L	Xp,r	Depth
-	IST	-		-	_991	_dee_		HZ_				
901205	1300	0.80	0.78	0.20	32.0	90.0	0.162	0.083	0.262	0.214	0.354	13.03
901205		0.58	0.55	0.17						0.336		
					••							
901206	0100	0.50	0.47	0.17	28.0	180.0	0.083	0.083	0.361	0.370	0.370	12.97
901206	0700	0.48	0.45	0.18	14.0	-180.0	0.093	0.074	0.389	0.379	0.521	13.62
901206		0.46				-178.0					_	
901206	1900	0.41	0.37	0.18	-2.0	-180.0	0.074	0.074	0.485	0.498	0.498	13.16

901207		0.38	0.34	0.17		-172.0						
901207 901207		0.36	0.32 0.34			-180.0 -178.0						
901207		0.40	0.36			-172.0						
,4284,	.,,,	0.40	0.30	4.10	-0.0	-4/2.0	0.003	4.4.4	V50	0.370	0.334	13.24
901208	0100	0.72	0.71	0.15	22.0	90.0	0.230	0.240	0.214	0.159	0.167	13.78
901208		1.57	1.54		2.0					0.229		
901208	1300	2.08	2.01	0.50	8.0					0.213		-
901208	1900	2.05	2.00	0.42	14.0	90.0	0.142	0.152	0.207	0.151	0.163	13.32
901209	0100	2.06	2.02	0.43	22.0	90.0	0.152	0.142	0.211	0.167	0.191	14.05
901209	0700	2.10	2.05	0.44	22.0				_	0.146		
901209		1.74	1.69	0.40		-170.0						
901209	1900	1.27	1.23	0.29	18.0	-176.0	0.113	0.093	0.237	0.217	0.298	13.12
001210	0100					-172.0						
901210 901210		0.95 0.72	0.89 0.69	0.34		-176.0						
901210		0.72	0.49	0.23	_	-180.0						
901210		0.51	0.47	0.20	_	-90.0						
,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,		0.52	0.47	0.20		- 30.0				0.301	0.333	
901211	0100	1.29	1.27	0.24	40.0	90.0	0.181	0.181	0.193	0.199	0.199	13.77
901211	0700	1.26	1.24	0.25	38.0					0.148		
901211	1300	1.19	1.16	0.26	28.0	90.6	0.152	0.132	0.225	0.215	0.257	13.62
901211	1900	0.91	0.89	0.21	24.0	-174.0	0.142	0.074	0.238	0.191	0.381	13.04
901212	-	0.74	0.71	0.21		-170.0						
901212		0.59	0.56	0.19		-168.0					_	
901212		0.50	0.46	0.18		-172.0						
901212	1900	0.43	0.39	0.16	8.0	-176.0	0.074	0.074	0.409	0.505	0.505	13.05
901213	0100	0.46	0.43	0.16	-2.0	-90.0	0 082	0 083	0 280	0 440	0 460	
901213		0.41	0.43	0.16	-18.0					0.435		
901213		0.40	0.37	0.16		-170.0						
901213		0.34	0.32	0.13		-144.0						
, , , , , ,		0.54	0.52						0.402	V. J. I	0.572	23.20
901214	0100	1.11	1.07	0.29	56.0	90.D	0.201	0.220	0.266	0.224	0.264	13.45
901214	0700				34.0	90.0	0.142	0.220	0.206	0.130	0.303	13.79
901214	1300	1.56	1.54	0.27	24.0	90.0	0.142	0.240	0.178	0.150	0.251	13.35
901214	1900	1.24	1.22	0.24	20.0	90.0	0.123	0.123	0.194	0.184	0.184	13.48
901215												
901215												
901215						-90.0						
901215	1900	1.09	1.04	0.31	0.0	-90.0	U.15Z	9.152	U. 2 93	0.279	0.279	13.45
901216	0100		0.70	0 22	-6.0	-00 0	0 142	0 152	0 200	0 274		
901216												
901216												
901216												
		- / -				J						
9°1217	0100	0.52	0.51	0.12	14.0	90.0	0.240	0.240	0.226	0.177	0.177	13.02

(Sheet 4 of 18)

						Disposion Fr				Reflection			
•		_	and He									n	
Date			Emo, 1		9,1	, p, r	£.:	E:	Zee	Xp,1	Xp, r	Depth	
-	EST_	4-			des	_der_							
901217	4744	0.76	0.74	0.19	34.0	90.0	0 171	0.171	0.253	0.237	0.237	11.82	
901217		0.63	0.74	0.13	24.0		_	0.152					
901217		0.59	0.57		18.0			0.152					
PULL!	1900	0.39	4.37	0.10	14.4	,	4.4/2	4.300	4.4.0				
901218	0100	0.55	0.53	0.14	10.0	-176.0	0.152	0.152	0.267	0.240	0.240	12.83	
901218		0.46	0.44			-176.0							
901218		0.41	0.38		-12.0			0.074					
901218		0.55	0.52			-90.0							
301470	1300	9.33	4.32	4.20	-34.4	- 50.0			4.00-	*****			
901219	0100	0.54	0.51	0.17	-46.0	-90.0	0.123	0.093	0.326	0.223	0.365	12.68	
901219		0.53	0.50	0.19	-58.0			0.103					
901219		0.51	0.49		-10.0			0.093					
901219		1.05	1.02	0.23	8.0			0.181					
,0141,	2,00	1.00			•.•					******			
901220	0100	1.17	1.15	0.21	16.0	90.0	0.181	0.181	0.186	0.185	0.185	13.07	
901220		1.46	1.44	0.28	16.0			0.181					
901220		1.53	1.51	0.24	12.0			0.181					
901220		1.58	1.55		8.0			0.142					
901220	1900	1.36	1.33					V.2-4			•••		
901221	0100	1.56	1.53	0.30	12.0	-9 0.0	0.152	0.123	0.196	0.131	0.198	13.17	
901221		1.52	1.48	0.35		-174.0							
901221		1.55	1.52	0.31	-6.0	_		0.123					
301221	1300	1.33	1.76	0.31	-0.0	,,,,,		*****					
901222	01.00	1.35	1.32	0.30	-14.0	-90.0	0.123	0.113	0.227	0.159	0.189	13.22	
901222		1.34	1.30	0.31	-4.0			0.103					
901222		1.05	1.01	0.27	-8.0			0.142					
901222		1.03	1.00	0.25	-4.0			0.123					
PULLEZ	1900	1.05	1.00	0.23	7.0	70.0		V. 2		******			
901223	0100	0.89	0.86	0.26	-2.0	-90.0	0.113	0.083	0.306	0.234	0.439	13.28	
901223		1.11	1.06	0.31	0.0			0.152					
901223		1.01	0.96	0.31	0.0			0.152	– .				
901223		0.91	0.88	0.24	-6.0			0.093					
901224	0100	0.82	0.76	0.29	-2.0	-140.0	0.093	0.093	0.385	0.328	0.328	13.27	
901224		0.91	0.86	0.29	-24.0	-90.0	0.093	0.093	0.332	0.283	0.283	12.95	
901224	1300	0.93	0.88	0.28	-14.0	90.0	0.093	0.093	0.322	0.258	0.258	13.30	
901224		1.87	1.84	0.34	30.0		0.152	0.210	0.187	0.106	0.273	13.18	
	-												
901225	0100	1.56	1.52	0.35	30.0	90.0	0.152	0.240	0.231	0.151	0.350	13.73	
901225	0700	1.18	1.15	0.25	30.0			0.240					
901225	1300	1.09	1.06	0.27	32.0	90.0	0.093	0.093	0.253	0.289	0.289	13.49	
901225	1900	1.05	1.02	0.25	-8.0	90.0	0.083	0.083	0.241	0.186	0.186	12.89	
901226	0100	1.02	0.96	0.34	-10.3	-168.0	0.083	0.083	0.358	0.390	0.390	13.77	
901226	0700	0.94	0.90	0.27	-14.0	-172.0	0.083	0.083	0.295	0.303	0.303	13.07	
901226	1300	1.17	1.14	0.29	6.0	90.0	0.083	0.083	0.255	0.293	0.293	13.69	
901226	1900	1.21	1.18	0.26	6.0	90.0	0.191	0.201	0.218	0.191	0.207	12.97	
901227					16.0	90.0	0.191	0.093	0.220	0.175	0.289	13.97	
901227					16.0	90.0	0.181	0.191	0.209	0.174	0.211	13.19	
901227					12.0	90.0	0.162	0.162	0.202	0.170	0.170	13.74	
901227	1900	1.79			12.0	90.0	0.152	0.152	0.166	0.143	0.143	13.06	
901228	0100	1 00			14.0	-90.0	0 112	0 122	0 217	n 170	0 200	12 67	
901228						-172.0							
901228						-170.0							
901228						180.0							
******	7300	4.04	J. 70	4.21			~.423	203	4.6/7	J. 273	426.0		
901229	0100	1.04	0.97	0.37	10.0	-180.0	0.103	0.103	0.379	0.452	0.452	13.82	
			-	_		ŕ							

(Continued)

(Sheet 5 of 18)

		Wave Height			21-		-					
8								STATE Y		******		Dench
Date		~=-	mo,i	Emp, r	9,1		7:1	تر بروگ اند	Zeo		4p, z	Depth
	244											
901229	0700	1.08	1.02	0.35	16.0	180.0	0.103	0.103	0.341	0.317	0.317	13.60
901229	1300	1.16	1.11	0.32	10.0	-176.0	0.093	0.093	0.287	0.254	0.254	13.43
901229	1900	1.06	1.01	0.32	2.0	-176.0	0.093	0.093	0.316	0.311	0.311	13.31
901230	0100	1.00	0.95	0.31		-9 0.0						
901230	0700		0.81			-90 .0						
901230		0.83	0.78	0.27						0.324		
901230	1900	0.75	0.69	0.29	-10.0	-132.0	0.093	0.093	0.424	0.373	0.373	13.23
901231 901231			0.62		-12.0 36.0	176.0				0.127		
901231			1.42		22.0					0.151		
7 01431	1300	1.40	1.42	V.33	22.0	70.0	0.131	0.210	4.234	0.431	U. 2	43.79
910101	0100	1 38	1.35	0.31	20.0	90.0	0.201	0.240	0.226	0.227	0.317	12.91
910101		1.41			18.0					0.199		
910101			1.13	0.23	12.0			_		0.150		
910101		1.18	1.14	0.29	10.0					0.202		
910102	0100	1.03	1.00	0.24	4.0	-90.0	0.093	0.093	0.235	0.231	9.231	12.82
910102	0700	1.15	1.10	0.34	4.0	-166.0	0.162	0.162	0.305	0.331	0.331	14.28
910102	1300	1.16	1.13	0.28	18.0					0.281		
910102	1900	1.27	1.22	0.36	16.0	-174.0	0.171	0.181	0.295	0.248	0.295	13.96
910103			0.91	0.20		-90.0						
910103		0.78	0.74			-174.0						
910103		0.63				-90.0						
910103	1900	0.73	0.69	0.22	a .u	-178.0	0.123	0.103	0.311	0.303	0.380	13.81
910104	0100	0.57	0.54	0.18	6.0	-180.0	0.103	0 103	0 326	0 327	0.327	13.07
910104		1.22	1.19		34.0					0.165		
910104		1.34	1.32		34.0					0.174		
910104		1.05	1.03			90.0			_	-	_	
910105	0100	1.05	1.03	0.20	20.0	90.0	0.181	0.240	0.197	0.154	0.196	13.40
910105	0700	1.18	1.15	0.24	14.0	90.0	0.201	0.201	0.209	0.199	0.199	13.65
910105		1.03	1.00		8.0					0.215		_
910105	1900	0.97	0.94	0.24	2.0	- 9 0.0	0.152	0.152	0.251	0.261	0.261	13.39
910106				0.24		-176.0						
910106		0.61	0.58			-90.0						
910106 910106		0.47		0.18 0.18		-178.0 -90.0						
ATOTOR	1740	0.50	0.46	4.19	-4.0	-30.0	J.443	4.113	J. J70	J. 43/	v.=3/	+3.1U
910107	0100	0.52	0.48	0.21	-8.0	-176.0	0.113	0.113	0.427	0.456	0.456	13.70
						-178.0						
						90.0						
910107	1900	2.92	2.87	0.52	10.0	90.0	0.123	0.240	0.179	0.130	0.334	13.47
910108	0100	3.00	2.93	0.63	12.0	90.0	0.123	0.113	0.213	0.177	0.198	14.22
						90.0						
910108	1300	3.01	2.97	0.54	14.0	90.0	0.123	0.132	0.182	0.143	0.169	14.00
910108	1900	2.84	2.79	0.48	6.0	90.0	0.093	0.240	0.172	0.131	0.394	13.39
		_										
910109 910109	0100	3.11	3.05	0.59	0.0	90.0	0.093	0.093	0.195	0.137	0.137	14.19
910109	1300	2.51	2.35	0.32		90.0						
910109	TAGG	1.43	1.75	U.44	-19.0	-190.0	v. u=3	J. U#3	U. 245	V.213	v. Z13	13.33
910110	0100	1 40	1 40	0 52	22 0	-17A .∩	0.091	0.003	0.127	0 335	0 335	14.04
	~~~	4.47		7.32		-, -, -	_, _,	J. J.J				_~

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		u,	ve He	ehe	Dir	ection	Pre	GUEDCY	- 1	eflect	10n	
Date	Time		E.c.i		92,1		4	£2,2	Ž-	Xn (	Xp,x	Depth
	IST				_des	des		<u> </u>		-, q-	~9,4	
910110	0700	1.51	1.44	0.46	18.0	-176.0	0.103	0.103	0.321	0.368	0.368	13.50
910110	1300	1.49	1.43	0.44		-172.0						
910110	1900	1.15	1.09	0.37	16.0	-174.0	0.093	0.093	0.337	0.435	0.435	13.32
910111 910111		1.47	1.42		20.0	-180.0				0.264		
910111		1.64	1.59		12.0					0.234		
910111		2.00	1.92		0.0					0.234		
710111	1900	2.00	1.92	0.36	9.0	- 30.0	0.123	0.123	4.273	V. 202	J . 482	13.31
910112	0100	2.39	2.28	0.70	0.0	-90.0	0.113	0.113	0.305	0.313	0.313	13.57
910112	0700	1.66	1.52	0.66	0.0	-172.0	0.103	0.103	0.431	0.490	0.490	13.57
910112	1300	1.41	1.27	0.60	0.0	-174.0	0.113	0.103	0.469	0.491	0.549	13.37
910112	1900	1.16	1.04	0.52	0.0	-172.0	0.113	0.113	0.501	0.494	0.494	13.44
910113		1.16	1.05			-172.0						
910113		1.43	1.35	0.46	26.0					0.313		
910113		1.14	1.09	0.32		90.0						
910113	1900	1.08	1.02	0.35	30.0	156.0	0.171	0.171	0.342	0.362	0.362	13.61
910114	0100	0.87	0.83	0.25	28.0	-174.0	0 171	0 171	0 300	0 283	0 283	12 41
910114		0.74	0.69			166.0						
910114		0.55		0.20		-178.0						
910114		0.53		0.23		-174.0						
	•				• • • • • • • • • • • • • • • • • • • •	•						
910115	0100	0.49	0.45	0.21	-4.0	-174.0	0.064	0.064	0.475	0.593	0.593	12.99
910115	0700	0.45	0.41	0.19	-8.0	-170.0	0.064	0.064	0.479	0.487	0.487	13.78
910115		0.46	0.41	0.21		-176.0						
910115	1900	0.46	0.41	0.20	-12.0	-174.0	0.123	0.064	0.492	0.308	0.720	13.63
910116	0100	0.45	0.41	0.18	-8.0	-174.0	0 074	0 024	0 433	A 550	0 550	12 01
910116	-	1.75	1.62	0.65		-126.0						
910116		1.42	1.33	0.49		-110.0						
910116		1.08	0.97	0.47		-128.0						
910117	0100	0.78	0.72	0.30	-16.0	-112.0	0.113	0.113	0.412	0.415	0.415	12.94
910117	0700	0.65	0.56	0.33	-14.0	-142.0	0.103	0.103	0.586	0.653	0.653	13.94
910117	1300	0.45	0.41	0.18	-12.0	-178.0	0.113	0.113	0.450	0.431	0.431	12.88
910117	1900	0.43	0.39	0.17	-6.0	-174.0	0.113	0.113	0.447	0.484	0.484	13.74
910118 910118		0.36	0.33	0.15		-180.0						
910118		0.37	0.34	0.13 0.12		-180.0 178.0						
910118		0.25	0.22	0.12	_	180.0						
710440	1300	0.23	0.22	V.11	-2.0	100.0	0.403	0.034	0.301	0.301	0.501	13.31
910119	0100	0.18	0.17	0.08	-10.0	-178.0	0.103	0.054	0.498	0.456	0.698	12.76
910119			0.18			-176.0						
910119	1300	0.24	0.23	0.09	14.0	180.0	0.103	0.054	0.408	0.435	0.692	12.78
910119	1900	0.28	0.26	0.11	14.0	-150.0	0.162	0.103	0.414	0.235	0.530	13.41
									<b>.</b>			
910120			0.23	–		-180.0						
910120			0.44		32.0					0.251		
910120 910120		0.78	0.75 0.58	0.19 0.24	20.0	90.0 -136.0				0.206		
******	7.20M	J. 43	4.35	J. 44	20.0	~134.0	V. 22U	J. UBJ	V. 410	V. ZZI	v . <del>v 34</del>	13.47
910121	0100	0.54	0.47	0.26	-4.0	-138.0	0.093	0.093	0.562	0.597	0.597	13.25
910121		0.46		0.22		-140.0						
910121		0.53	0.49		60.0	90.0	0.230	0.230	0.430	0.403	0.403	13.30
910121	1900	1.45	1.37	0.48	38.0	90.0	0.162	0.171	0.351	0.300	0.379	13.68

(Continued)

(Sheet 7 of 18)

		V	ve He	leht	Dir	ection	_Ire	GUGACT		eflect	LOD_	
Date	Time	E _{mo}	Emp, 1	Emo, r	P, 1	P, r	40.1	fp,r	Xmo		Xp, r	Depth
	IST	<u> </u>	_		des	_ <u>dee</u> _						
910122	0100	1.35	1 27	0.46	36.0	<b>9</b> 0 0	0 162	0 171	0 366	0 286	0.402	13 #4
910122				0.53							0.338	
910122				0.58	32.0						0.434	
910122				0.47	26.0						0.467	
910123 910123			0.88		32.0							
			0.65	0.27	22.0							
910123 910123		0.55	0.30	0.25	14.0 10.0	-					0.584	
												•••••
910124		0.39		0.19		-172.0						
910124		0.36		0.16		-176.0						
910124		0.36	0.32	0.16		-174.0						
910124	1900	0.36	0.32	0.16	-4.0	-178.0	0.093	0.093	0.504	0.492	0.492	12.79
910125	0100	0.36	0.32	0.15	-2.0	-172.0	0.093	0.093	0.472	0.500	0.500	13.86
910125	0700	1.84	1.79	0.44	40.0	90.0	0.162	0.181	0.243	0.154	0.269	13.22
910125	1300	1.57	1.49	0.49	32.0	90.0	0.181	0.181	0.328	0.370	0.370	13.74
910125	1900	1.10	1.05	0.33	22.0	90.0	0.132	0.132	0.312	0.324	0.324	12.96
910126	0100	0.90	0.85	0.31	22.0	170.0	0 152	0 142	0 162		0 410	
910126		_	0.72	0.22		180.0		– –				
910126		0.68	0.64	0.23		-180.0						
910126			0.51	0.19		-180.0						
,,,,,,,,,,,				4.27	•		*****			•	0.577	
910127						-176.0						
910127		0.34	0.31			-174.0						
910127		0.33	0.30	0.14		-178.0						
10127	1900	0.36	0.33	0.14	-16.0	-176.0	0.132	0.132	0.434	0.455	0.455	13.11
910128	0100	0.49	0.46	0.18	-1A.D	-90.0	0.132	0.142	0.385	0.406	0 427	13 34
910128		0.63	0.57			-90.0						
910128		0.51	0.48			-90.0						_
910128	1900		0.55	0.32		-130.0						
									_			
910129			0.57			-108.0						
910129		0.61	0.54			-132.0					-	
910129 910129		0.6 <b>\$</b> 0.69				-90.0						
,,,,,,	1700	0.09	v.03	0.23	-4.0	-122.0	V.132	0.113	0.301	0.421	0.500	13.73
10130	0100	0.84	0.80	0.26	-6.0	-90.0	0.162	0.171	0.329	0.331	0.379	12.93
10130	0700	0.71	0.65	0.28	-6.0	-172.0	0.152	0.152	0.431	0.447	0.447	14.08
					24.2							
)10201 )10201		0.81	0.80	0.15	26.0	90.0 166.0	0.152	0.152	0.185	0.171	0.171	12.56
10201		0.00	0.03	4.25	44.0	100.0	0.102	0.113	0.277	0.209	U.331 .	13.70
10202	0100	0.54	0.53	0.13	6.0	90.0	0.152	0.113	0.255	0.213	0.313	12.75
910202						176.0	0.103	0.103	0.359	0.439	0.439	13.71
						-104.0						
10202	1900	0.54	0.50	0.21	-12.0	-110.0	0.103	0.113	0.418	0.481	0.502	13.54
110202	0100	0.50	6 44	0.20	-12.0	-112.0						
10203						-108.0						
10203		0.44	0.45 0.41	0.20	-10.0	-116.0	0.103	0.001	0.476 I	U.JEL	0.341 ) N 498 1	13.44
		0.54	0.48	0.24	-16.0	-112.0	0.113	0.113	0.498	0.513 i	).513 1	3.28
				0.23	-20.0	-136.0	0.103	0.103	0.581	0.632	1.632	13.17
10204				0.20	-10.0	-110.0	0.113	0.103	0.490	D. 469	3.520 1	13.22
10404	1340	Ų. 37	u.32	0.17	-10.0	-136.0	0.103	U.103	0.527	D.532 (	0.532 1	13.12

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(Continued)

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		W	ave He	leht	Dix	ection	Žīs	QUEDCY	R	eflecti	on	
Date	Time		Sec. 1									Depth
						400			_	Xp,1	-p,.	
910204	1900	0.41	0.37	0.18	-16.0	-108.0	0.113	0.113	0.481	0.426	0.426	13.13
910205	0100	0.41	0.35	0.20	-24.0	-134.0	0.113	0.103	0.557	0.551	0.641	13.47
910205	9700	0.43	0.38	0.19	-28.0	-110.0	0.103	0.113	0.506	0.471	0.535	13.21
910205	1300	0.48	0.42	0.23	-14.0	-136.0	0.113	0.123	0.537	0.487	0.610	13.44
910205	1900	0.51	0.46	0.23	-14.0	-132.0	0.113	0.113	0.499	0.534	0.534	13.20
910206	0100	0.60	0.52	0.30	-16.0	-138.0	0.113	0.113	0.575	0.559	0.559	13.74
910206	0700	0.63	0.56	0.29	-20.0	-132.0	0.113	0.113	0.514	0.509	0.509	13.18
910206	1300	0.56	0.49	0.28	-18.0	-136.0	0.113	0.113	0.569	0.591	0.591	13.51
910206	1900	0.53	0.48	0.24	-14.0	-128.0	0.113	0.123	0.511	0.450	0.537	13.12
910207	0100	0.51	0.45	0.25	-16.0	-138.0	0.113	0.113	0.569	0.633	0.633	13.77
910207	0700	0.51	0.45	0.24	-12.0	-134.0	0.123	0.123	0.522	0.565	0.565	13.18
910207	1300	0.54	0.47	0.25	-12.0	-140.0	0.113	0.113	0.534	0.583 (	3.583	13.32
910207	1900	0.56	0.50	0.25	-6.0	-138.0	0.123	0.113	0.504	0.486	0.541	13.17
910208	0100	0.66	0.60	0.27	4.0	-144.0	0.113	0.113	0.446	0.512	3.512	13.92
910208	0700	1.99	1.90	0.59	30.0	90.0	0.171	0.171	0.308	0.330	3.330	13.42
910209	1300	1.33	1.26	0.43	18.0	90.0	0.210	0.123	0.340	0.336	. 435	13.53
910209	1900	0.90	0.85	0.29	16.0	180.0	0.123	0.142	0.341	0.342	1.426	13.22
910210	0100	0.71	0.66	0.26	10.0	178.0	0.123	0.123	0.386	0.457	. 457	13.67
910210	0700	0.67	0.63	0.24	2.0	-178.0	0.113	0.113	0.384	0.389	. 389	13.41
910211	1300	0.64	0.63	0.15	14.0	90.0	0.240	0.230	0.244	0.204	. 206	13.34
910211	1900	0.56	0.54	0.16	8.0	-180.0	0.162	0.162	0.294	0.280	. 280	13.48
910212	0100	1.11	1.07	0.31	26.0	90.0	0.210	0.210	0.286	0.277	.277	13.48
910212	0700	1.69	1.64	0.42	30.0	90.0	0.152	0.171	0.258	0.212	.281	13.84
910212	1300	1.16	1.13	0.27	28.0					0.219		
910212	1900	0.91	0.87	0.26	26.0					0.216		
910213	0100	0.64	0.61	0.18	16.0	174.0	0.123	0.123	0.302	0.322 0	. 322	13.13
910213	0700	0.49	0.46	0.16	0.0					0.277 0		
910213	1300	0.35	0.33	0.11	-18.0					0.320 0		
910213		0.27	0.25	0.09	-20.0	-				0.361 0		
	•											
910214	0100	0.41	0.38	0.15	-20.0	-106.0	0.132	0.132	0.399	0.408 0	. 408	12.95
910214				0.30						0.524 0		
910214										0.467 0		
910214										0.539 0		
							••					••••
910215	0100	0.53	0.49	0.22	-12.0	-104.0	0.103	0.093	0.452	0.419 0	. 305	12.94
910215		0.41								0.503 0		
										0.494 0		
910215				0.26	66.0					0.241 0		
				**		,,,,				<b></b>		
910216	0100	0.95	0.90	0.29	60.0	90.0	0.201	0.240	0.316	0.293 0	.426	12.91
910216	-				60.0					0.252 0		
910216					62.0					0.245 C		
910216										0.292 0		
<del></del>												
910217	0100	0.39	0.37	0.11	-2.0	90.0	0.083	0.083	0.307	0.361 0	.361	12.73
910217										0.550 0		
910217					-12.0	176.0	0.093	0.064	0.392	0.303 0	. 581	2.52
910217										0.594 O		
		J. #/		4.44			,-			>- U		

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(Sheet 9 of 18)

-			V	l aba	D1 =	207100	7			- 61	1	
Data	*1		Emp. 1	THE .		ection		<u>guency</u>		TIECL		Deneb
	IST	****		~	deg	op, r		72.2	700	Xp,1		Depth
910218	0100	0.31	0.29	0.11	-24.0	<b>-9</b> 0.0	0.093	0.064	0.389	0.377	0.663	12.80
910218	0700	0.28	0.26	0.12	-10.0	170.0	0.083	0.093	0.473	0.592	0.661	13.61
41 001 0	1 200					- 00 0						
910219 910219		0.46	0.43	0.16	-36.0 -30.0					0.369		
310213	1300	0.47	0.44	0.17	-30.0	-90.0	0.181	0.083	u.3//	0.376	0.327	13.31
910220	0100	0.44	0.41	0.15	-18.0	~90.0	0.171	0.171	0.364	0.400	0.400	13.28
910220	0700	0.44	0.41		-28.0					0.324		
910220	1300	0.40	0.38	0.15	-34.0	-90.0	0.152	0.152	0.387	0.372	0.372	12.97
910220	1900	0.39	0.37	0.12	-30.0	-90.0	0.152	0.152	0.324	0.260	0.260	13.04
01.0004												
910221 910221		0.40	0.37	0.14	-30.0 2.0					0.389		
910221		0.56	0.64							0.244		
910221	-		0.56		12.0					0.386		
910222	0100	0.66	0.62	0.23	6.0	-130.0	0.171	0.113	0.372	0.327	0.455	13.65
910222		0.52	0.50	0.16		-90.0						
910222		0.43	0.40			-138.0						
910222	1900	0.37	0.34	0.12	-14.0	-104.0	0.113	0.113	0.361	0.366	0.366	12.78
910223	0100	1.02	0.95	0.36	20.0	90.0	0 230	0 240	0 376	0.396	0 419	13 RG
910223			2.24		30.0					0.159		
910223	1300	2.19	2.12		32.0					0.188		
910223	1900	2.41	2.36	0.49	18.0	90.0	0.142	0.171	0.207	0.171	0.266	13.14
910224		1.58	1.53		18.0					0.236		
910224 910224		1.38	1.35	0.29 0.37	12.0 8.0					0.192		
910224		1.81	1.75	0.47	-2.0					0.299		
,,,,,,,,		2.42	2			,,,,	0.223	0.113	0.200	0.233	0.277	13.03
910225	0100	1.68	1.60	0.52	2.0	178.0	0.113	0.113	0.322	0.394	0.394	13.81
910225	0700	1.22	1.16	0.38	10.0	-178.0						
910225		1.26	1.21	0.33	14.0					0.290		
910225	1900	1.10	1.05	0.33	12.0	180.0	0.132	0.132	0.310	0.355	0.355	13.27
910226	0100	1.02	0.98	0.29	8.0	174 0	0 142	0 112	n 203	0.295	0 346	19 67
910226		1.64	1.58	0.45	20.0					0.295		
910226		1.44	1.40	0.36	20.0					0.256	-	
910226		1.07	1.02	0.31	20.0					0.320		
910227			0.76		18.0					0.284		
910227		_	0.77		28.0					0.428		
910227 910227		0.57	0.55	0.16	22.0 30.0					0.304		
910227	1300	0.44	0.41	0.10	30.0	166.0	0.113	0.113	U. 355	0.443	U.443	13.79
910228	0100	0.37	0.34	0.13	12.0	-90.0	0.113	0.103	0.395	0.382	0.485	12.95
910228			0.28			-90.0						
910228					8.0	174.0	0.103	0.103	0.419	0.404	0.404	12.78
910228	1900	0.47	0.42	0.22	12.0	-180.0	0.093	0.093	0.519	0.589	0.589	13.82
910301												
910301 910301						-90.0 -90.0						
910301				0.26	-6.0	-90.0	0.103	0.103	0.429	0.34U   0.437	0.34U ) 0.437 1	14./9
			••••		J				- 1 - 2 - 2	3r '		
910302	0100	1.10	1.05	0.32	-16.0	-90.Q	0.142	0.142	0.307	0.313	0.313	12.73
910302	0768	1.38	1.28	0.51	-14.0	-90.0	0.123	0.123	0.394	0.401	0.401	3.80
910302	1300	1.16	1.11	0.35	-10.0	-90.0	0.113	0.113	0.312	0.309 (	3.309	12.58

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(Continued)

										<b>41</b> 1		
Basa	**					etion	111	Wency		ITAGET		Banash.
Date			40,i	Po,r	9,1 988	p, r	Ti.	£9, z	X==0	Xp,1	Xp. z	
910302	1900	1.02	0.94	0.39	-12.0	-112.0	0.113	0.113	0.416	0.458	0.458	13.80
910303	0100	0.93	0.89	0.27	-6.0	-90.0	0.113	0.113	0.307	0.299	0.299	12.74
910303	0700	1.01	0.93	0.40	-6.0	-90.0	0.113	0.113	0.435	0.428	0.428	13.66
910303		0.87	0.83			-90.0						
910303		1.34	1.24			-116.0						
910304	0100	1.29	1.22	0.42	-12.0	-116.0	0.103	0.093	0.345	8.292	0.339	12.82
910304		1.18	1.09			-118.0						
910304		1.15	1.07			-90.0						
910304		1.11	0.98			-134.0		-				
910305	0100	0.98	0.88	0.43	-16.0	-124.0	0.093	0.083	0.485	0.434	0.535	13.23
910305		0.96	0.87			-140.0						
910305	_	0.88	0.81	0.34		-136.0						
910305		0.87	0.80			-138.0						
				0,00								
910306			0.69			-142.0						
910306	0700	0.80	0.73	0.32	2.0	-138.0	0.103	0.103	0.439	0.412	0.412	13.19
910306	1300	0.78	0.70	0.34	2.0	-140.0	0.103	0.103	0.482	0.488	0.458	13.19
910307	0100	0.82	0.73	0.37	-4.0	-146.0	0.103	0.103	0.516	0.519	0.519	13.33
910307	0700	0.70	0.64	0.29	-4.0	-90.0	0.103	0.103	0.454	0.392	0.392	12.98
910307	1300	0.55	0.49	0.27	-2.0	-142.0	0.093	0.093	0.549	0.532	0.532	13.34
910307	1900	0.49	0.45	0.18	-4.0	-138.0	0.093	0.093	0.404	0.449	0.449	13.18
910308	0100	0.58	0.55	0.20	6.0	90.0	0.240	0.103	0.358	0.255	0.420	13.70
910308	0700	1.01	0.97	0.26	30.0	90.0	0.191	0.201	0.269	0.266	0.290	13.19
910308	1300	0.91	0.87	0.26	34.0	90.0	0.191	0.191	0.295	0.306	0.306	13.44
910308	1900	0.85	0.81	0.24	16.0	90.0	0.181	0.181	0.300	0.316	0.316	13.05
910309	0100	0.78	0.75	0.23	22.0	90.0	0.201	0.201	0.309	0.297	Q.297	13.64
910309	0700	1.23	1.19	0.32	22.0					0.226		
910309	1300	1.08	1.03	0.33	22.0	90.0	0.181	0.181	0.323	0.366	0.366	13.50
910309	1900	0.93	0.89	0.27	22.0	90.0	0.132	0.142	0.302	0.262	0.296	13.06
910310	0100	0.78	0.74	0.24	18.0	170.0	0.142	0.142	0.331	0.332	0.332	13.64
910310		1.13	1.09	0.30	18.0					0.310		
910310		1.18	1.13	0.33	18.0					0.295		
910310	1900	1.20	1.14	0.36	20.0	168.0	0.171	0.152	0.317	0.307	0.344	13.29
910311	0100	1.29	1.20	0.47	32.0	162.0	0.162	0.171	0.397	074	0.406	13.92
910311		1.44			30.0					0.293		
910311		1.66	1.57	0.54	30.0			_		0.346		
910311					28.0	90.0					-	
910312	0100	1.45	1.37	0.46	30.0	90.0	0.162	0.171	0.339	0.291	0.347	13.81
910312						172.0					-	
910312						174.0						
910312						176.0						
			V. WA	4.44								
910313			0.73			176.0						
910313						176.0						
910313			0.93		10.0							
910313	1900	1.09	1.01	0.40	2.0	172.0	0.083	0.083	0.401	0.419	0.419	13.51
910314	0100	0.96	0.90	0.35	-2.0	-90.0	0.083	0.093	0.386	0.396	0.428	13.35
910314						174.0	0.132	0.132	0.468	0.462	0.462	13.75
910314	1300	0.93	0.88	0.30	16.0	176.0	0.123	0.113	0.343	0.307	0.438	13.25

(Sheet 11 of 18)

					- B4 -					-41		
						ection					ion	n-a-a-b
Date	ISI	-			9, L	p,r	7:	-	<b>Xeo</b>	Xp,1	Xp. z	Depth
910314	1900	0.97	0.89	0.39	18.0	170.0	0.113	0.113	0.441	0.434	0.434	13.84
910315	0100	1.26	1.17	0.47	18.0	176.0	0.103	0.103	0.401	0.448	0.448	13.37
910315	0700	1.48	1.37	0.57	22.0	172.0	0.093	0.093	0.414	0.537	0.537	14.06
910315	1300	1.63	1.55	0.52	20.0	90.0	0.103	0.103	0.333	0.383	0.383	13.32
910315	1900	1.78	1.65	0.65	22.0	174.0	0.093	0.093	0.390	0.492	0.492	14.15
910316	0100	1.82	1.73	0.57	20.0	• • • • •				0.388		
910316	0700	1.72	1.58	0.69	18.0					0.539		
910316	1300	1.46	1.37	0.50	14.0	170.0	0.083	0.083	0.367	0.401	0.401	13.16
910316	1900	1.35	1.22	0.59	14.0	178.0	0.083	0.093	0.487	0.472	0.607	14.19
910317		1.30	1.22	0.44	10.0					0.351		
910317	0700	1.29	1.18		8.0					0.442		
910317	1300	1.20	1.12	0.42	6.0					0.377		
y10317	1900	1.30	1.16	0.58	6.0	180.0	0.074	0.074	0.506	0.575	0.575	14.15
910318	0100	1.29	1.20	0.49	4.0	164.0	0.083	0.083	0.410	0.450	0.450	12.90
910318	0700	1.21	1.09	0.51	4.0	178.0	0.083	0.083	0.466	0.552	0.552	13.90
910318	1300	1.41	1.32	0.49	-2.0	-90.0	0.074	0.074	0.374	0.379	0.379	12.76
910318	1900	1.53	1.39	0.62	8.0	-144.0	0.083	0.083	0.446	0.443	0.443	14.06
910319		1.20	1.12		0.0			•		0.340		
910319	0700	0.96	0.85		0.0	-144.0						
910319		0.96	0.89	0.35	-2.0					0.341		
910319	1900	0.84	0.76	0.37	2.0	90.0	0.093	0.093	0.497	0.511	0.511	14.04
910320	0100	0.62	0.56	0.25	10.0	90.0	0.083	0.083	0.453	0.463	0.463	13.16
910320	0700	0.51	0.46	0.23	8.0	174.0	0.083	0.093	0.500	0.501	0.625	13.57
910320	1300	0.44	0.40	0.18	6.0	158.0	0.083	0.083	0.447	0.439	0.439	13.02
910320	1900	0.46	0.41	0.20	12.0	170.0	0.083	0.983	0.486	0.493	0.493	13.66
910321		0.48	0.43		8.0					0.405		
910321		0.52		0.24	8.0					0.604		
910321		0.51		0.22		-180.0						
910321	1900	0.51	0.46	0.23	2.0	162.0	0.083	0.083	0.492	0.481	0.481	13.33
910322	0100	0.48	0.43	0.23	4.0	-166.0	0.083	0.074	0.544	0.406	0.606	13.52
910322	0700	0.45	0.41	0.18	0.0	156.0	0.074	0.083	0.446	0.398	0.450	13.11
910323	1300	0.82	0.76	0.31	18.0	152.0	0.132	0.132	0.410	0.395	0.395	13.74
910323		0.99	0.93		16.0				-	0.363		
910324	0100	0.87	0.79	0.38	14.0	174.0	0.103	0.103	0.479	0.496	0.496	13.94
910324	0700	0.81	0.76	0.28	10.0	-90.0	0.113	0.113	0.371	0.352	0.352	13.09
910324	1300	0.83	0.75	0.37	8.0	176.0	0.113	0.113	0.494	0.509	0.509	13.73
						-90.0						
						90.0						
					26.0	90.0	0.171	0.162	0.287	0.302	0.339	13.11
910325						166.0						
910325	1900	0.48	0.46	0.15	12.0	162.0	0.093	0.103	0.334	0.394	0.427	13.09
910326						174.0			-			
910326						166.0 176.0						
910326						-178.0						
910327	0100	0.67	0.61	0.26	10.0	174.0	0.093	0.103	0.426	0.420	0.454	13.63

(Continued)

(Sheet 12 of 18)

(Continued)

	· · · ·	¥.	ve Sei	eht	Dir	ection	Pre	quenc T	R	flect	ion	
Date	Time			L _{mo, r}	1p, 1		40.1	Lp,r			Xp,z	Depth
	ISI_				_308	494						_
910327	0700	0.73		0.31		-178.0						
910327	1300	0.80	0.75	0.30		162.0						
910327	1900	0.73	0.65	0.33	0.0	-178.0	0.093	0.093	0.498	0.498	0.498	13.43
910328						138.0						
910328			0.57			-174.0						
910328			0.51	0.21		-90.0						
910328	1900	0.52	0.46	0.23	-22.0	-150.0	0.093	0.083	0.307	0.313	0.333	13.39
910329	0100	0.47	0.44	0.18	-6.0	-00 0	0 003	0.083	0.410	0 405	n 478	12 90
910329		0.51	0.45	0.23				0.093				
910329			0.64		-28.0			0.240	-			
910329		0.76	0.67	0.37	-24.0			0.132				
,1032,	1,000	V	0.07	•.•	24.0		*****					
910330	0100	0.81	0.75	0.32	-20.0	-90.0	0.132	0.132	0.424	0.431	0.431	12.84
910330		0.86	0.76			-130.0						
910330		1.84	1.76					0.171				
910330		1.59	1.50		22.0		_	0.132				
												•
910331	0100	1.09	1.04	0.31	10.0	146.0	0.123	0.103	0.300	0.239	0.340	13.04
910331	0700	1.15	1.09	0.37	12.0	164.0	0.123	0.132	0.343	0.347	0.433	14.01
910331	1300	1.19	1.15	0.29	14.0	90.0	0.201	0.201	0.253	0.269	0.269	13.01
910331	1900	1.28	1.22	0.40	16.0	166.0	0.171	0.181	0.326	0.320	0.351	14.15
910401	0100	1.03	1.00	0.27	14.0	168.0	0.113	0.113	0.271	0.305	0.305	12.98
910401	0700	1.02	0.94	0.39	10.0	172.0	0.123	0.123	0.416	0.430	0.430	13.85
910401	1300	0.79	0.76	0.23	10.0	160.0	0.113	0.093	0.304	0.269	0.343	12.90
910401	1900	0.66	0.60	0.28	14.0	174.0	0.093	0.093	0.473	0.524	0.524	13.96
910402			0.60		8.0			0.103				
910402			0.73	0.27	8.0			0.113				
910402		0.56	0.53		8.0			0.113				
910402	1900	0.52	0.49	0.18	6.0	174.0	0.132	0.132	0.362	0.411	0.411	13.63
010403	2100	0.50	0 40		4.0	-180.0		0 107	0 174	D 411	0 433	77 14
910403								0.103				
910403 910403		0.57	0.53	0.19 0.17	4.0			0.113				
910403		0.53		0.18	0.0			0.113				
310403	1300	0.33	0.50	0.10	0.0	100.0	0.113	V.113	0.350	0.3/9	0.3/9	13.03
910404	0100	0.56	0.53	0.18	-4.0	160.0	0.113	0.083	0.332	0.322	0.401	13.26
910404		0.61	0.58					0.093				
910404	-	0.55	0.52			-102.0						
910404		0.57	0.54			-90.0				-		
910405	0100	0.53	0.48	0.22	-12.0	-148.0	0.093	0.093	0.447	0.520	0.520	13.36
910405	0700	0.53	0.49	0.19	-12.0	-90.0	0.093	0.093	0.380	0.364	0.364	13.10
910405	1300	0.56	0.51	0.23	-14.0	-140.0	0.093	0.093	0.464	0.490	0.490	13.20
910405	1900	0.51	0.47	0.19	-20.0	-90.0	0.093	0.093	0.406	0.415	0.415	13.13
						-146.0						
910406			0.41	0.15		-90.0						
910406			0.46	0.21		<b>-9</b> 0.0						
910406	1900	0.50	0.47	0.18	-12.0	-100.0	0.103	0.103	0.395	0.370	0.370	13.09
		<u>.</u>										
910407						-144.0						
910407						-90.0						
910407	-		0.33			-144.0						
910407	1400	0.35	0.32	0.14	-32.0	-100.0	U.113	U.113	U.429	U.396	U.396	13.03

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(Continued)

		y.	ve Re	ght	Dire	ction	Tre	GUEDCY	R	eflection	
Date	Time		E _{so,1}						X		Depth
	EST		===		_des	_448_					<u> </u>
910408	0100	0.36	0.33	0.14	-38.0	-108.0	0.113	0.113	0.431	0.464 0.464	13.57
910408	0700	0.34	0.31	0.12	-38.0	- <b>9</b> 0.0	0.113	0.113	0.398	0.373 0.373	12.94
910408	1300	0.33	0.31	0.14	-32.0	-106.0	0.113	0.113	0.443	0.479 0.479	13.47
910408	1900	0.35	0.32	0.13	-30.0	-90.0	0.113	0.113	0.412	0.377 0.377	13.00
910409	0100	0.38	0.35	0.16	-34.0	-90.0	0.113	0.113	0.461	0.437 0.437	13.57
910409	0700	0.48	0.44	0.17	-34.0	-90.0	0.162	0.162	0.395	0.418 0.418	12.93
910409	1300	0.51	0.47	0.19	-26.0					0.416 0.482	
910409	1900	0.51	0.48	0.18	-24.0	- <b>9</b> 0.0	0.113	0.113	0.377	0.367 0.367	12.95
		_									
910410		0.32	0.46	0.23	-26.C					0.489 0.489	_
910410		0.45	0.42	0.17	-36.0					0.388 0.388	
910410		0.39	0.36		-26.0					9.457 0.457	
910410	1900	0.38	0.35	0.15	-34.0	-90.0	0.113	0.113	0.422	0.414 0.414	13.17
<b>61</b> 0444						00.0					
910411		0.69	0.66	0.22	44.0					0.336 0.336	_
910411		1.82	1.74	0.52	42.0					0.214 0.365	
910411	_	0.99	0.94	0.29	24.0					0.276 0.387	
910411	1900	0.55	0.52	0.19	10.0	104.0	0.162	0.152	0.367	0.387 0.477	13.38
910412	0100	0.49	0.46	0.15	4.0	-172 0	0 142	A 171	0 221	0.338 0.425	13 30
910412		0.79	0.77	0.19	18.0					0.205 0.233	
910412		1.40	1.36	0.33	26.0					0.242 0.242	
910412		1.03	0.99	0.29	24.0					0.313 0.313	
710-12	1,00	1.43	0.77	0.23	24.0	104.0	0.102	0.102	0.497	0.313 0.313	13.00
910413	0100	1.11	1.08	0.26	14.0	90 0	0 201	0 171	0 241	0.234 0.307	11 10
910413		0.86	0.83	0.23	14.0					0.302 0.302	
910413		0.80	0.78	0.20	6.0					0.283 0.283	
910413		0.83	0.79	0.26	2.0					0.283 0.369	
		•.••				0			0.320	0.205 0.507	
910414	0100	0.78	0.75	0.21	0.0	-90.0	0.152	0.171	0.285	0.268 0.293	13.00
910414		0.65	0.61	0.22	-14.0					0.395 0.395	
910414	1300	0.53	0.51	0.15	-12.0					0.364 0.364	
910414	1900	1.50	1.41	0.52	22.0					0.417 0.417	
910415	0100	1.33	1.30	0.29	14.0	90.0	0.113	0.103	0.224	0.204 0.245	13.00
910415	9700	1.28	1.22	0.40	14.0	176.0	0.113	0.113	0.325	0.365 0.365	13.87
910415	1300	1.00	0.96	0.26	6.0	-90.0	0.113	0.083	0.270	0.236 0.283	12.88
910415	1900	0.84	0.77	0.32	0.0	178.0	0.123	0.113	0.415	0.411 0.445	14.10
910416	0100	0.71	0.68	0.20	-4.0	-90.0	0.103	0.113	0.294	0.258 0.283	12.76
910416		0.68	0.62	0.28	-12.0	-90.0	0.113	0.103	0.452	0.426 0.616 1	13.84
910416	1300	0.53	0.50	0.16	-10.0	-90.0	0.123	0.123	0.327	0.334 0.334 2	12.81
910416	1900	0.62	0.58	0.21	2.0	-90.0	0.123	0.132	0.352	0.346 0.405	14.12
										0.224 0.267 1	
910417					-12.0					0.355 0.412	
910417					-18.0					0.290 0.534 1	
910417	1900	0.47	0.43	0.19	-22.0	-90.0	0.132	D.064	0.450	0.420 0.784 1	13.98
8184											
910418			1.00		18.0					0.255 0.255 1	
910418					32.0					0.251 0.251 1	
910418	7.400	1.66	1.60	0.45	30.0	9U.0	J.132	U.152	J. 281	0.280 0.280 1	14.11
910419	0100	1.78	1.73	0 42	22 0	90.0		0 174			
910419			1.73		22.0 20.0					0.282 0.282 1	
910419		1.53	1.47		14.0					0.248 <i>0.248 1</i> 0.290 0.290 1	-
910419		1.59		0.41	10.0					0.290 0.290 1 0.295 0.295 1	
\744TA	. 744	4.47	1.33	2.41	10.0	7U.U		e.103	v. 40/	0.433 U.ZY3 1	3.72

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(Continued)

		W	eve Be	Leht	Dir	ection	Îre	<b>QUENCY</b>	R	flect	on	
Date	Time			E.s.				fp, t			Xp,z	Depth
	EST				_398	_498_						_
910420	0100	1.60		0.40	8.0	-90 0	0 142	0 103	0 258	0.211	0 271	13.84
910420		1.84		0.42						0.223		
910420				0.55						0.209		
910420				0.70						0.155		
******	1,00	3.47	2.77	0.70		20.0	V.223	0.240	V. 654			
910421				0.62	-	90.0						
910421				0.48		90.0						
910421		1.36		0.52		-178.0						
910421	1900	0.85	0.79	0.32	20.0	-178.0	0.123	0.113	0.401	0.325	0.394	13.22
910422	0100	0.61	0.55	0.26	18.0	180.0	0.123	0.113	0.475	0.516	0.523	13.99
910422	0700	0.45	0.41	0.17	6.0	-180.0	0.123	0.123	0.422	0.423	0.423	13.00
910422	1300	0.48	0.43	0.21	4.0	-90.0	0.113	0.113	0.484	0.506	0.506	13.75
910422	1900	0.49	0.45	0.20	-4.0	-90.0	0.113	0.113	0.440	0.422	0.422	12.90
910423	0100	0 57	0 50	0 27	2.0	-140.0	0 113	0 113	n 433	0 585	0 585	11 80
910423				0.18		-90.0	_	-				
910423			0.41			176.0						
910423				0.19		168.0						
910424		_		0.23		174.0				0.452		
910424	0700	0.54	0.50	0.21	2.0	-90.0	0.123	0.093	0.413	0.342	U. 44Y	13.03
910425	1300	0.47	0.44	0.15	6.0	90.0	0.240	0.093	0.345	0.306	0.476	13.54
910425	1900	0.45	0.42	0.17	10.0	-180.0	0.083	0.093	0.401	0.440	0.491	13.53
910426	0100	0 46	0.44	0.15	10.0	176.0	0 093	0 003	0 345	0.369	0 169	12 22
910426		0.47	0.43			-180.0						
910426		0.50	0.47			176.0						
910426		0.43	0.39	0.18	-2.0					0.492		
910427					-4.0					0.515		
910427		0.43								0.443		
910427 910427		0.54	0.50	0.19	2.0 -2.8	-						
91U4Z/	1900	0.50	0.30	V.24	-2.0	2/4.0	4.673	V. U73	0.470	0.309	0.309	13.00
910428	0100	0.63	0.59	0.23	2.0	165.0	0.074	0.074	0.391	0.479	0.479	12.91
910428		0.60	0.53	0.26	0.0	172.0	0.083	0.083	0.495	0.547	0.547	13.66
910428		0.56		0.21	0.0	166.0	0.083	0.083	0.394	0.371	0.371	12.97
910428	1900	0.53	0.49	0.20	-26.0	-90.0	0.083	0.083	0.406	0.435	0.435	14.04
910429	0100	0.52	0.48	A 10	-30.0	-90 0	0 003	0.083	n 104	0.377	0 444	13 04
910429		0.80				-90.0						
						-90.0						
910430	1900	0.53	0.49	0.20	4.0	180.0	0.074	0.074	0.413	0.472	0.472	14.00
910501	4100	0.46	n 49	0.18	2.0	168.0	0.074	0.07A	0.427	n 501	n <b>59</b> 1	13.00
910501						172.0						
910501						168.0						
910501						180.0						
						176.0						
910502						172.0						
						172.0						
910502	1900	0.37	0.34	0.13	-4,Q	172.Q	0.074	0.074	0.390	0.493	0.493	13.80
910303	0100	0.38	0.35	0.14	-2.0	176.0	0.132	0.074	0.401	0.298	0.501	13.24
						172.0						
		_										

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(Continued)

				1		/	<b>w</b>			-61	1	
Da	T1		ave Re	FEDE		ection	111	QUEDCY		Liect	100	Beneh
	IST	700	eo,i	Emp, r	p,i	op, r	7:1	Ti.	A00	^p, L	^p, :	Depth
910503	1300	0.42	0.39	0.14	18.0		_			0.328		
910503	1900	0.57	0.55	0.15	46.0	90.0	6.191	0.201	0.270	0.238	0.263	13.66
910504				0.11	36.0					0.256		
910504		0.30			4.0					0.267		
910504		0.30		0.09	-6.0 -2.0					0.367		
910504	1900	0.30	0.29	V. U <del>y</del>	-2.0	-90.0	0.201	0.073	0.304	0.201	V. J.J	43.43
910505	0100	0.40	0.39	0.11	14.0	-90.0	0.171	0.171	0.286	0.284	0.284	13.47
910505		0.40			18.0					0.249		
910505		-	0.35		-14.0					0.274		
910505	1900	0.41	0.39	0.12	-8.0	-90.0	0.191	0.191	0.299	0.307	0.307	13.39
910506	0100	0.49	0.46		_	-90.0						
910506		0.68			-18.0					0.333		
910506	1900	0.39	0.38	0.12	-14.0	-90.0	0.171	0.132	0.317	0.248	0.372	13.15
A1 A					-22 2	-138.0			0 394		0 161	13 42
910507		0.40			-22.0					0.343		
910507 910507		0.35			62.0					0.262		
910507		0.50			28.0					0.239		
,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,		••••	****	••••		20.0		*****				
910508	0100	0.45	0.43	0.14	0.0	-90.0	0.210	0.083	0.336	0.211	0.537	13.68
910508	0700	0.41	0.39	0.12	0.0	150.0	0.142	0.093	0.305	0.246	0.351	13.00
910508	1300	0.40	0.38	0.14	0.0	180.0	0.093	0.093	0.358	0.435	0.435	13.71
910508	1900	0.40	0.39	0.13	-8.0	-90.0	0.162	0.093	0.325	0.282	0.412	13.08
910509		0.42				-144.0						
910509		0.42			-14.0					0.230		
910509 910509		0.38			-14.0 -12.0					0.296		
310203	1900	0.40	0.34	0.10	-11.0	-90.0	0.103	0.103	0.400	V. 200	0.200	43.20
910510	0100	0.47	0.44	0.14	-10.0	-90.0	0.201	0.201	0.312	0.290	0.290	13.66
910510		0.47				-90.0						
910510						-144.0						
910510	1900	0.39	0.37	0.15	-18.0	-142.0	0.132	0.132	0.408	0.480	0.480	13.33
910511	0100	0.93	0.91	0.21		90.0						
910511		0.95		0.20		90.0						
910511	_	0.93		0.25	8.0					0.305		
910511	1900	0.69	0.66	0.20	2.0	172.0	U.123	0.123	0.302	0.329	0.329	13.51
010514	0100	0 74	0.71	0.22	2.0	164 0	0 104	0 112	0 105	0.343	0 416	13 20
910512 910512		0.74				-148.0						
910512						-146.0						
						-148.0						
910513	0100	0.59	0.56	0.19	-8.0	162.0	0.103	0.103	0.337	0.323	0.323	12.90
						178.0						
						-90.0						
910515	1900	0.29	0.27	0.09	-52.0	-90.0	0.181	0.191	0.329	0.336	0.346	14.27
						- 44 -						
						-90.0						
ATA210	1100	0.34	0.31	0.15	20.0	90.0 90.0	0.420	0.410	0.334	0.309	0.336	17 84
						176.0						
ATA310	1700	V.37	9.37	U.1/	-4.0	A/8.U	4.1/1	J. 192	J. JUB	J. JJE	J. 374	-4.43
910517	<b>Q100</b>	0.46	g.44	0.11	-6.0	-90.0	0.162	0.171	0.250	0.228	0.242	13.01
~==##										<b></b>		
					,,		۵,					

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Dete			Smo, 1	2,00	7.1	op, z	2.1	- <u>- 2:</u> -	Zeo	Xp,i	Xp,z	Depth
	131	•										—
910517	0700	0.44	0.42	0.13	-4.0	-90.0	0.201	0.210	0.301	0.267	0.304	13.70
910517	1300	9.36	0.35	. –		-90.0						
910517	1900	0.38	0.36	0.12	-6.0	-90.0	0.191	0.181	0.335	0.289	0.326	13.80
910518		0.32	0.30	_	-12.0			0.113				
910518		0.31	0.29		0.0			0.123				
910518		1.40	1.37		18.0			0.201				
910518	1900	2.21	2.16	9.46	22.0	90.0	0.142	0.142	0.213	0.186	0.186	13.87
910519	0100	2 22	2 17	0.48	20.0	90.0	0 113	0.113	n 223	0 243	B 243	11 95
910519		2.48			12.0			0.171				
910519		2.31	2.25		14.0			0.142				
910519		1.87	1.83	0.36	12.0			0.171				
910520	0100	1.65	1.60	0.39	6.0	176.0	0.093	0.093	0.242	0.199	0.199	14.04
910520	0700	1.54	1.51	0.32	2.0	-90.0	0.093	0.171	0.210	0.179	0.243	13.30
910521		1.00		0.29	-4.0			0.152		_		
910521	1900	0.92	0.88	0.26	-4.0	-90.0	0.123	0.162	0.294	0.230	0.352	12.97
910522	0100	0.86	0.80	0.31	-4 0	-90.0	0 122	0 112	A 185	0 102	0 102	19 76
910522		0.75	0.72	0.22	-8.0			0.142				
910522		0.67	0.62	0.25		-144.0						
910522		0.57	0.54	0.20	-8.0			0.123				
		_										
910523	0100	0.57	0.52	0.24	-6.0	-144.0	0.142	0.123	0.469	0.465	0.496	13.59
910523	0700	0.47	0.43	0.17	-20.0	-140.0	0.123	0.113	0.402	0.326	0.389	12.91
910523		0.48	0.43			-144.0						
910523	1900	0.40	0.36	0.17	-24.0	-138.0	0.123	0.113	0.479	0.442	0.516	13.24
010504	0100					-106.0	. 122					
910524 910524		0.40	0.36	0.17		-138.0						
910524		0.46	0.42	0.19		-142.0						
910524		0.41	0.38	0.17		-136.0						
		• • • •							•			•••
910525	0100	0.50	0.46	0.20	-12.0	-102.0	0.132	0.132	0.434	0.468	0.468	13.28
910525	0700	0.53	0.49	0.20	-12.0	-144.0	0.142	0.132	0.419	0.381	0.413	13.21
910525		0.51	0.47	0.21		-138.0						
910525	1900	0.47	0.43	0.19	-24.0	-138.0	0.142	0.142	0.449	0.453	0.453	13.49
A1 A E 2 C					. 44 . 4	-00 0						
910526 910526	-	0.53	0.49	0.21		-90.0 -140.0						
910526		0.51	0.47	0.23		-105.0						
910526		0.47	0.43	0.20		-112.0						
,,,,,,,,,	4200	••••					••••			0.420		••••
910527	0100	0.47	0.43	0.19	-32.0	-90.0	0.142	0.074	0.451	0.397	0.622	13.06
910527	0700	0.47	0.43	0.19	-32.0	-90.0	0.142	0.142	0.442	0.475	0.475	13.60
910529												
910529	1900	0.37	0.34	0.15	-14.0	-90.0	0.083	0.083	0.427	0.451	0.451	13.99
910530 910530												
910530												
910530						-144.0						
					-4.4		~.~~	~.~~		T. J.J.		
910531	0100	0.32	0.29	0.15	-24.0	-136.0	0.083	0.083	0.512	0.551	0.551	12.91
910531												
910531						-104.0						

(Sheet 17 of 18)

# (Concluded)

						ection						
Date	Time EST	H ₂₀	Eso, i	Hao, r	des des	des_	F:1	<u>L'i</u>	¥ <b>60</b>	x _{p,1}	Xp, z	Depth
910531	1900	0.35	0.33	0.13	-12.0	-90.0	0.093	0.103	0.397	0.354	0.406	13.79
910601	0100	0.33	0.30	0.14	-8.0	-178.0	0.093	0.093	0.466	0.455	0 455	13.13
910601	0700	0.32	0.30	0.11	-8.0	-90.0	0.293	0.093	0.373	0.360	0.360	13.58
910601	1300	0.32	0.29	0.12	-10.0	-90.0	0.093	0.093	0.425	0.424	0.424	13.20
910601	1900	0.29	0.27	0.11	-4.0	-172.0	0.093	0.093	0.411	0.410	0.410	13.75
910602	0100	0.31	0.28	0.12	-4.0	178.0	0.093	0.093	0.430	0.478	0.478	13.29

Appendix B: Time Series Graphs of Bulk Spectral Parameters

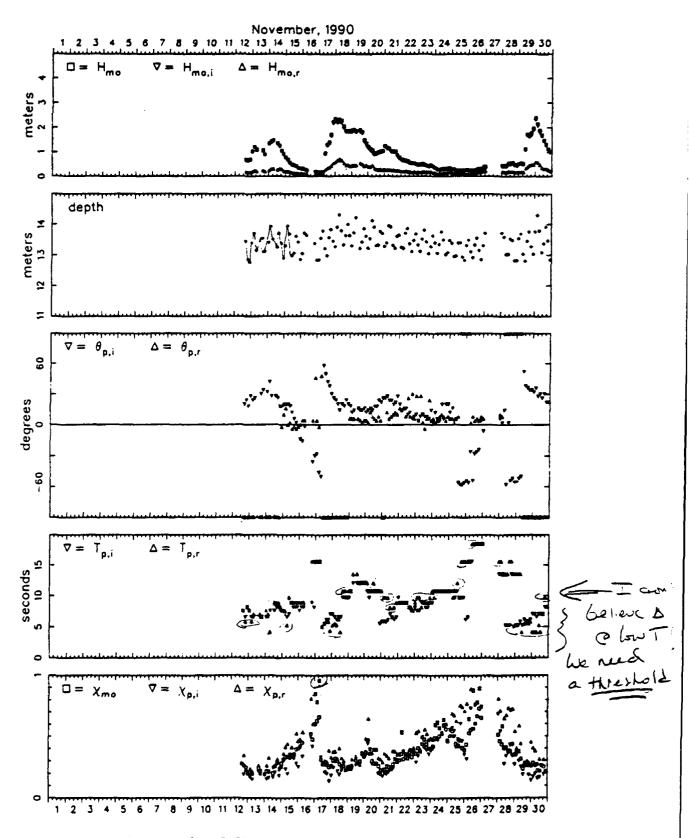


Figure B1. Bulk data for November 1990

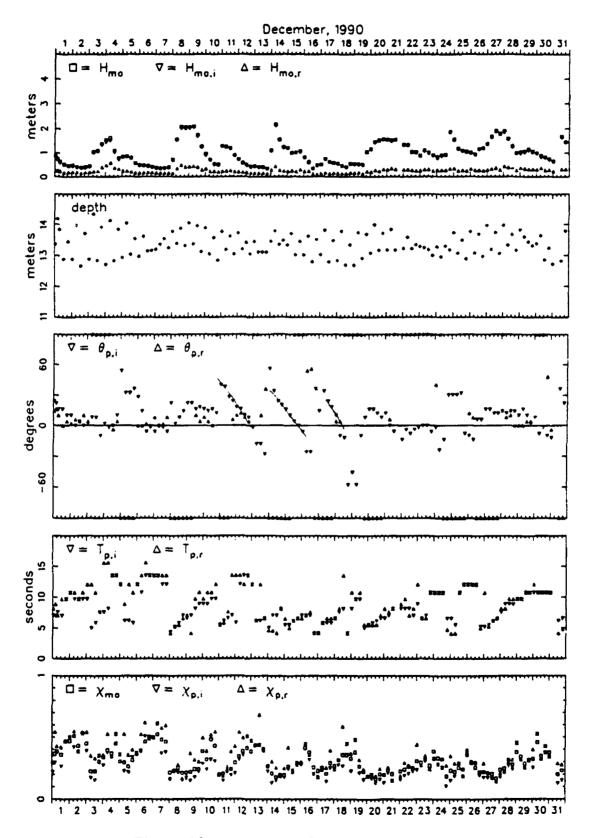


Figure B2. Bulk data for December 1990

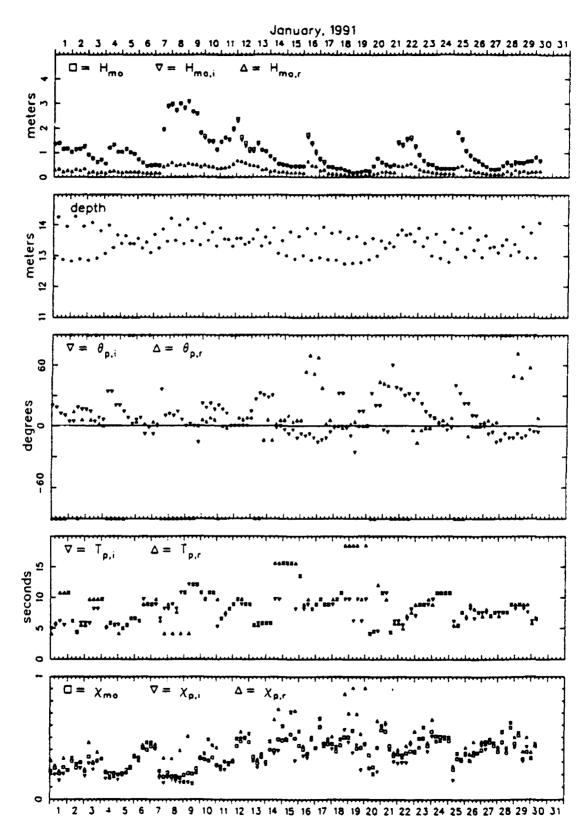


Figure B3. Bulk data for January 1991

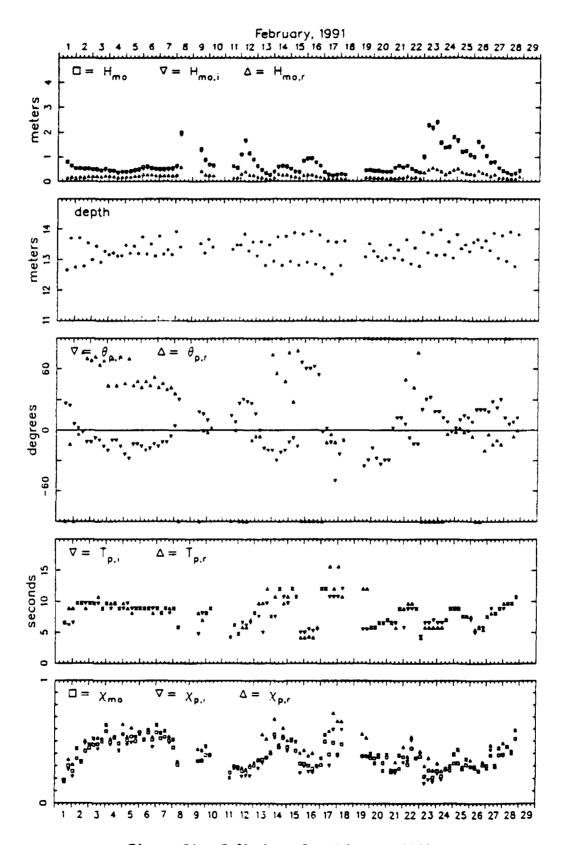


Figure B4. Bulk data for February 1991

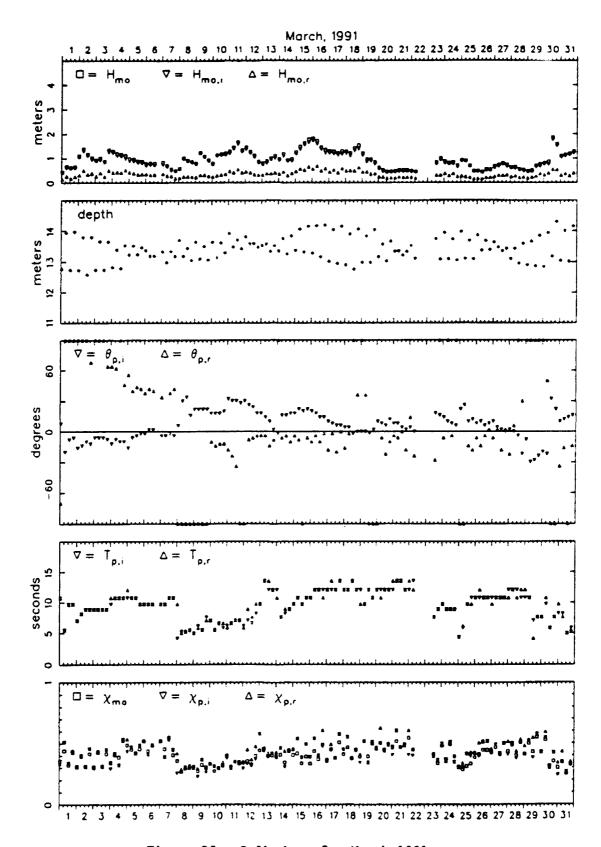


Figure B5. Bulk data for March 1991

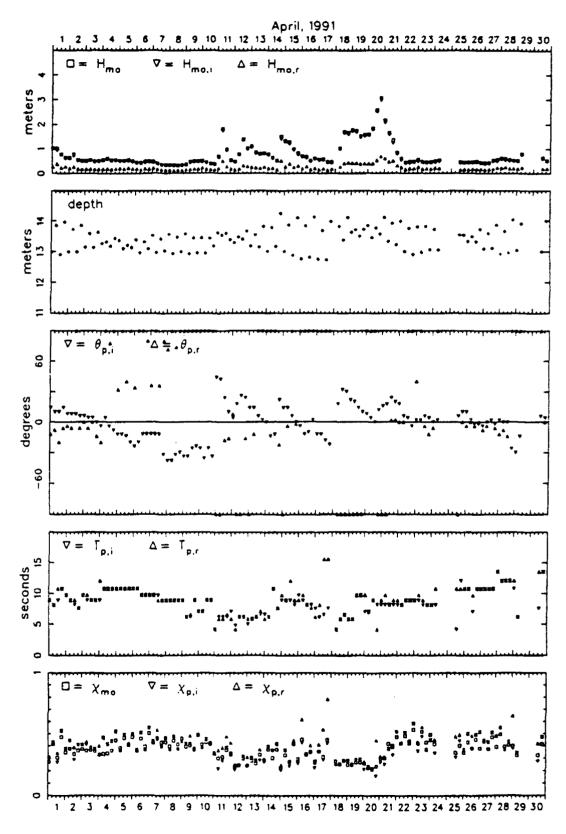


Figure B6. Bulk data for April 1991

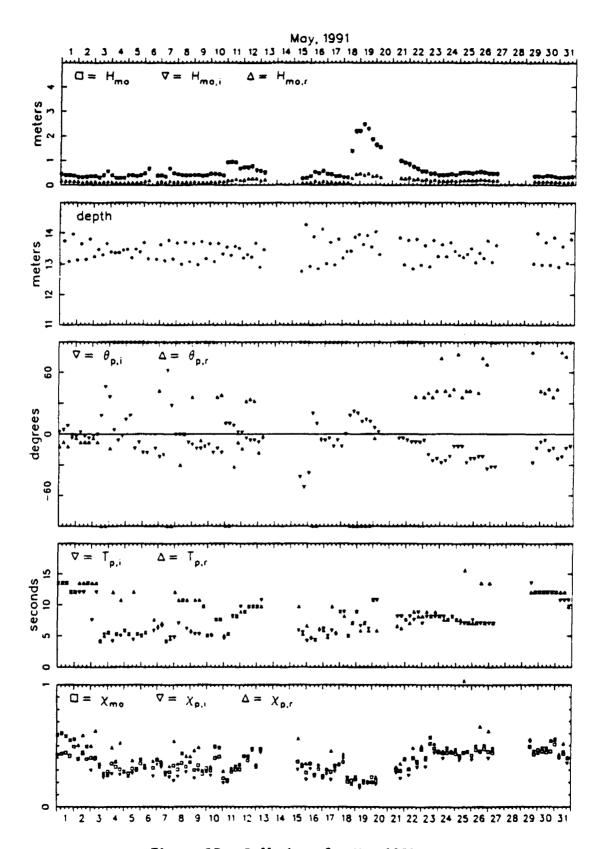


Figure B7. Bulk data for May 1991

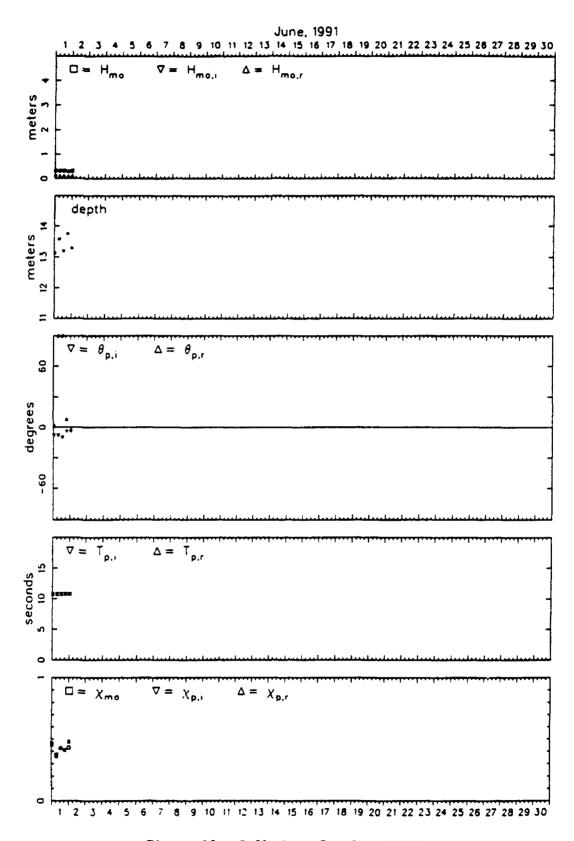


Figure 88. Bulk data for June 1991

Appendix C: A Derivation of the Maximum Likelihood Estimator

# Appendix C: A Derivation of the Maximum Likelihood Estimator

1. Under ideal circumstances, a single train of ocean surface waves can be represented as a sinusoid in the form*

$$\eta(x,y,t) = a\cos(k\cos\theta x + k\sin\theta y - \sigma t + \epsilon) \tag{C1}$$

where x and y are light-handed coordinates in a horizontal plane (at elevation z=0, where z is the vertical coordinate directed positive upward from the mean sea surface), t is time, a is the wave amplitude, k is radian wavenumber,  $\theta$  is the direction toward which the wave propagates and is measured counterclockwise (looking downward) from the positive x-axis,  $\sigma$  is radian wave frequency, and  $\epsilon$  is an initial phase. When linear wave theory is used, wavenumber and frequency are, for a given depth of water, uniquely related by the linear wave dispersion relation

$$\sigma^2 = gk \tanh kd \tag{C2}$$

where g is gravitational acceleration, and d is water depth. A natural sea can be considered an infinite sum of such waves so that sea surface displacement is represented generally as

$$\eta(x,y,t) = \sum_{n=1}^{\infty} a_n \cos(k_n \cos\theta_n x + k_n \sin\theta_n y - \sigma_n t + \epsilon_n)$$
 (C3)

For each index n, there is a unique set of  $a_n$ ,  $\sigma_n$ ,  $\theta_n$  and  $\epsilon_n$  that, for a given depth, completely determine the nature of the nth wave train (note that  $k_n$  is dictated by  $\sigma_n$  and d through the dispersion relation).

2. Because it can be rather awkward keeping track of this infinite number of four-variable sets, it is useful to have a form of book-keeping that is compact enough that even a very complicated sea can be quantified and depicted in a simple way. A common form of such book-keeping is the frequency-direction spectrum. In this method, a plane is gridded in even steps of the orthogonal coordinates  $\sigma$  and  $\theta$ , with each cell in the grid being of infinitesimal dimension  $\Delta\sigma$  by  $\Delta\theta$ . There is then a cell that corresponds to the  $\sigma_n$  and  $\theta_n$  of the  $n^{th}$  wave train so that the other two properties  $a_n$  and  $\epsilon_n$  of this wave train can be associated with that cell. Above the gridded  $\sigma$ - $\theta$  plane can be constructed surfaces that represent wave

A notation for this appendix is included in Appendix D

train properties. The most common of these is variance of sea surface displacement (which by linear wave theory is proportional to mean energy of a wave train) normalized by grid cell area. This variance density (sometimes called energy density) together with its coordinates in  $\sigma$ - $\theta$  space is the frequency-direction spectrum of sea surface variance  $E(\sigma,\theta)$ , which is most commonly sought. One could also build spectra of wave amplitude or phase, but wave energy is usually of greatest interest.

3. The variance of a single sinusoidal wave train of amplitude  $a_n$  is half the amplitude squared. By definition, this is the volume under the spectrum over one grid cell. This relation can be written

$$\frac{1}{2}a_n^2 = \int_{\theta_n - \frac{1}{2}\Delta\theta}^{\theta_n + \frac{1}{2}\Delta\theta} \int_{\sigma_n - \frac{1}{2}\Delta\sigma}^{\sigma_n + \frac{1}{2}\Delta\sigma} E(\sigma, \theta) d\sigma d\theta$$
 (C4)

The primary effort in most directional spectral estimation is the determination of  $E(\sigma,\theta)$  from time series of sea surface displacement at a few points in space, i.e., from a sparse sample of the left side of Equation C3 to an estimate of the integrand on the right side of Equation C4.

- 4. Preliminary theoretical considerations involve computation of a Fourier frequency transform of the covariance between the model sea surface at location x,y and time t and the sea surface at arbitrarily displaced coordinates x+X,y+Y and displaced time t+T. This process yields a useful relationship between the measurable frequency cross-spectra between two points in space and an integral with respect to direction of the frequency-direction spectrum. A good discussion of this process is given by Munk, et al. (1963)*, and the following is based on insights gained therefrom.
- 5. The covariance R(X,Y,T) between spatially and temporally separated sea surface displacements is found from the average over large reaches of space and long durations the product of the model for  $\eta(x,y,t)$  with the model for  $\eta(x+X,y+Y,t+T)$ . This can be expressed as

$$R(X,Y,T) = \frac{A \to \infty}{B \to \infty} \frac{1}{ABC} \int_{-\frac{c}{2}}^{\frac{c}{2}} \int_{-\frac{a}{2}}^{\frac{a}{2}} \int_{0}^{A} \eta(x,y,t) \eta(x+X,y+Y,t+T) dt dx dy$$

$$C \to \infty$$
(C5)

When the model Equation C3 is substituted, this expression becomes a triple

^{*} References for this appendix are listed in the main body of the report

integral of the product of two infinite sums. Its evaluation is time consuming but straightforward, and results in the rather simple expression

$$R(X,Y,T) = \sum_{n=1}^{\sigma} \frac{1}{2} a_n^2 \cos(k_n \cos \theta_n X + k_n \sin \theta_n Y - \sigma_n T)$$
 (C6)

The variance within the sum can be replaced with its spectral definition given by Equation C4, which leads to

$$R(X,Y,T) = \sum_{n=1}^{6} \left[ \int_{\theta_{n}-\frac{1}{2}\Delta\theta}^{\theta_{n}+\frac{1}{2}\Delta\theta} \int_{\sigma_{n}-\frac{1}{2}\Delta\sigma}^{\sigma_{n}+\frac{1}{2}\Delta\sigma} E(\sigma,\theta) \, d\sigma \, d\theta \right] \cos(k_{n}\cos\theta_{n}X + k_{n}\sin\theta_{n}Y - \sigma_{n}T)$$
 (C7)

The summation covers all conceivable bins in the infinitesimally gridded  $\sigma \cdot \theta$  domain and effectively links the edges of each integration region to form a continuous double integral over the bounds  $(0 \le \theta \le 2\pi \ , \ 0 \le \sigma \le \infty)$  of frequency-direction space. Hence, the covariance function becomes

$$R(X,Y,T) = \int_0^{2\pi} \int_0^{\pi} E(\sigma,\theta) \cos(k\cos\theta X + k\sin\theta Y - \sigma T) d\sigma d\theta$$
 (C8)

The trigonometric identity for the cosine of the sum of two angles can be used to isolate terms in  $\sigma T$  in Equation C8. If that result is regrouped and the order of integration reversed, the result is

$$R(X,Y,T) = \int_{0}^{\infty} \left[ \int_{0}^{2\pi} E(\sigma,\theta) \cos(k\cos\theta X + k\sin\theta Y) d\theta \right] \cos\sigma T d\sigma$$

$$+ \int_{0}^{\infty} \left[ \int_{0}^{2\pi} E(\sigma,\theta) \sin(k\cos\theta X + k\sin\theta Y) d\theta \right] \sin\sigma T d\sigma$$
(C9)

The bracketed term in the first integral on the right side of Equation C9 is the usual definition of the coincident spectrum, denoted  $C(X,Y,\sigma)$ , and the bracketed term in the second integral on the right side of Equation C9 is the quadrature spectrum  $Q(X,Y,\sigma)$ . The covariance function then becomes

$$R(X,Y,T) = \int_0^{\infty} \left[ C(X,Y,\sigma) \cos \sigma T + Q(X,Y,\sigma) \sin \sigma T \right] d\sigma \tag{C10}$$

A Fourier transform of the covariance function acts to isolate the coincident and quadrature spectra in the form

$$\int_{-\infty}^{\infty} R(X,Y,T) e^{-i\sigma T} dT = C(X,Y,\sigma) - iQ(X,Y,\sigma)$$
 (C11)

If the integral definitions of these spectra are substituted, one obtains

$$\begin{split} &C(X,Y,\sigma) - iQ(X,Y,\sigma) \\ &= \int_0^{2\pi} E(\sigma,\theta) \cos(k\cos\theta X + k\sin\theta Y) d\theta - i \int_0^{2\pi} E(\sigma,\theta) \sin(k\cos\theta X + k\sin\theta Y) d\theta \\ &= \int_0^{2\pi} E(\sigma,\theta) \left[ \cos(k\cos\theta X + k\sin\theta Y) - i\sin(k\cos\theta X + k\sin\theta Y) \right] d\theta \\ &= \int_0^{2\pi} E(\sigma,\theta) \left[ e^{-i(k\cos\theta X + k\sin\theta Y)} d\theta \right] d\theta \end{split}$$

- 6. The cross-spectra can usually be estimated from measurements because samples can be obtained often enough that frequency content is well-resolved. If samples could be obtained in space with equivalent coverage, Equation C12 could be Fourier transformed spatially to isolate the frequency-direction spectrum. The problem is that it is very difficult to obtain spatial sampling with sufficient density for Fourier transformation and only a few (order 10) spatial points are measured. An alternative approach is to create a model of  $E(\sigma,\theta)$  and employ the sparse available measurements to determine the model parameters. There are several ways to formulate such a model. Maximum Likelihood Estimation (MLE) is one of them.
- 7. In MLE, the combined amplitude and phase of a single wave train are modeled. This wave train has a unique frequency and direction, and so has a unique location in the frequency-direction plane used to define spectral elements. Spectral density is computed from the amplitude of this wave train. MLE is somewhat unique in that continuous distributions of energy density are not found. The estimator "looks" along a single discrete direction at a time to find, for each of a set of discrete frequencies, the most likely (maximum likelihood) amplitude of a wave moving in that direction. By looking along a number of adjacent discrete directions, an estimated directional spectrum can be constructed. Some features of this method, including its direction resolving ability, its ability to distinguish multiple wave trains and its behavior in relation to the number and spacing of the observing gages, must be deduced empirically by analyzing synthetic data imposed on a particular array design.
- 8. The purpose here is to outline the reasoning and mathematical underpinnings of MLE as applied to wave directional estimation. What follows is an expansion of what is covered in just a few lines in each of two papers

used for reference. One is by Davis and Regier (1977) and the other is by Oltman-Shay and Guza (1984).

9. The frequency-direction spectrum is found by trying to isolate the amplitudes of single plane waves, one wave train at a time. A single plane wave can be defined by Equation C1, but for the present method, it is desired to rewrite this expression using the Euler notation definition of cosine  $[\cos x - (e^{ix} + e^{-ix})/2] \implies$  that Equation C1 becomes

$$\eta(\mathbf{x}, \mathbf{y}, \mathbf{t}) = a \frac{1}{2} \left[ e^{i(\mathbf{k}\cos\theta\mathbf{x} + \mathbf{k}\sin\theta\mathbf{y} - \sigma\mathbf{t} + \epsilon)} + e^{-i(\mathbf{k}\cos\theta\mathbf{x} + \mathbf{k}\sin\theta\mathbf{y} - \sigma\mathbf{t} + \epsilon)} \right]$$

$$= \frac{1}{2} a e^{i\epsilon} e^{i(\mathbf{k}\cos\theta\mathbf{x} + \mathbf{k}\sin\theta\mathbf{y} - \sigma\mathbf{t})} + \frac{1}{2} a e^{-i\epsilon} e^{-i(\mathbf{k}\cos\theta\mathbf{x} + \mathbf{k}\sin\theta\mathbf{y} - \sigma\mathbf{t})}$$

$$= \frac{1}{2} D e^{i(\mathbf{k}\cos\theta\mathbf{x} + \mathbf{k}\sin\theta\mathbf{y} - \sigma\mathbf{t})} + \frac{1}{2} D^* e^{-i(\mathbf{k}\cos\theta\mathbf{x} + \mathbf{k}\sin\theta\mathbf{y} - \sigma\mathbf{t})}$$
(C13)

where  $D=ae^{i\epsilon}$  is known as the complex amplitude and the asterisk means complex conjugate. Because this is only a change in notation and not in substance, wave train properties given above will remain the same, but the notation will change. Where a squared amplitude appeared (as in covariance estimates) previously as  $a^2$ , it will now be  $DD^*$ . The infinite suite of wave trains that defines a sea surface has the notation

$$\eta(x,y,t) = \sum_{n=1}^{\infty} \frac{1}{2} D_n e^{i(k_n \cos\theta_n x + k_n \sin\theta_n y - \sigma_n t)} + \frac{1}{2} D_n^* e^{-i(k_n \cos\theta_n x + k_n \sin\theta_n y - \sigma_n t)}$$
(C14)

Then the variance of the nth component wave is from Equation C4

$$\frac{1}{2}a_{n}^{2} = \frac{1}{2}D_{n}D_{n}^{*} \tag{C15}$$

and the covariance function R(X,Y,T) is

$$R(X,Y,T) = \sum_{n=1}^{\bullet} \frac{1}{2} D_n D_n^* \cos(k_n \cos\theta_n X + k_n \sin\theta_n Y - \sigma_n T)$$
 (C16)

All subsequent expressions, including those for the continuous frequencydirection spectrum and the cross-spectra, will be identical to those given above.

10. Data are expected to be some measure of sea surface displacement  $\eta$  which may be direct measurements or derived from surface corrected time series of pressure recorded at some level in the water column. Here it is assumed

that direct measurements have been made. There will be in general a set of N gages, indexed  $n=1,2,\ldots,N$ , from each of which is collected an R-point time series sampled at time interval  $\Delta t$  for a duration of  $R\Delta t$ . Gages are deployed in a two-dimensional array in a pattern that follows, in two dimensions, the guidance given quite nicely by Davis and Regier (1977) for one dimensional arrays. The frequency content of the data is needed, so a conventional discrete Fourier transform is computed. For the  $n^{th}$  gage, located at horizontal position  $x_n, y_n$ , the Fourier transform at the  $q^{th}$  frequency is, in accordance with procedures given by Bendat and Piersol (1971) or Jenkins and Watts (1968),

$$X_{q}(x_{n}, y_{n}) = \sum_{r=1}^{R} \eta_{r}(x_{n}, y_{n}) e^{-i2\pi q r/R}$$
  $q=1,2,...,\frac{R}{2}$  (C17)

where  $\eta_r$  is the data value at the  $r^{th}$  time step. The model of wave amplitude D is based on the coefficients of the Fourier series representation of sea surface displacement. Fourier series coefficients can be found directly from Fourier transforms. For the  $q^{th}$  frequency  $\sigma_q$  of the transformed data at location  $\mathbf{x}_n, \mathbf{y}_n$ , the Fourier coefficient can be written

$$A_{q}(x_{n}, y_{n}) - iB_{q}(x_{n}, y_{n}) = \frac{2}{R}X_{q}(x_{n}, y_{n})$$
 (C18)

which is valid at all frequencies except zero and the Nyquist, which two cases are ignored with very little penalty in this derivation.

11. The heart of the maximum likelihood method is finding an expression to represent the complex amplitude  $D=ae^{i\epsilon}$  of a single wave train at frequency  $\sigma_q$  (as dictated in practice by the Fourier transform above) and traveling in the single look direction  $\alpha$ . Because Fourier coefficients intrinsically contain amplitude and phase information on a frequency-by-frequency basis, it is reasonable to formulate a model for  $ae^{i\epsilon}$  as a linear combination of the N Fourier series coefficients at frequency  $\sigma_q$  determined from the N gages in the array. A linear combination means a weighted sum, so the model takes the form

$$D = a e^{i\epsilon} = \sum_{n=1}^{N} w_n(\alpha) \left[ A_q(x_n, y_n) - i B_q(x_n, y_n) \right]$$

$$= \sum_{n=1}^{N} w_n(\alpha) \frac{2}{R} X_q(x_n, y_n)$$
(C19)

where the  $w_n(\alpha)$  are a set of N complex weights unique to the look direction  $\alpha$ , which will be determined by the optimization scheme described below. The variance of the modeled wave train is given by Equation C15, and, if the model Equation C19 is substituted, the variance becomes

$$\frac{1}{2}a^2 = \frac{1}{2} \left[ \sum_{n=1}^{R} w_n(\alpha) \frac{2}{R} X_q(x_n, y_n) \right] \left[ \sum_{m=1}^{R} w_m(\alpha) \frac{2}{R} X_q(x_m, y_m) \right]^*$$
 (C20)

where the summing index is changed on the second sum to distinguish the various terms after the multiplication is carried out. Taking the complex conjugate of the second sum, carrying out the term-by-term multiplication and recombining the results leads to

$$\frac{1}{2}a^{2} = \frac{1}{2} \left[ \sum_{n=1}^{N} w_{n}(\alpha) \frac{2}{R} X_{q}(x_{n}, y_{n}) \right] \left[ \sum_{m=1}^{N} w_{m}^{*}(\alpha) \frac{2}{R} X_{q}^{*}(x_{m}, y_{m}) \right] 
= \frac{1}{2} \sum_{n=1}^{N} \sum_{m=1}^{N} w_{n}(\alpha) w_{m}^{*}(\alpha) \frac{4}{R^{2}} X_{q}(x_{n}, y_{n}) X_{q}^{*}(x_{m}, y_{m})$$
(C21)

The contribution of this variance to the frequency-direction spectrum is unique in that it represents that piece of the total variance in a region of area  $\Delta\theta$  by  $\Delta\sigma$  centered at direction  $\alpha$  and frequency  $\sigma_q$  in the frequency-direction plane. When normalized by the incremental area  $\Delta\sigma\Delta\theta$  of the frequency-direction plane, an estimate of the frequency-direction spectrum  $\hat{E}(\sigma_q,\alpha)$  due to this wave train can be written

$$\hat{E}(\sigma_{\mathbf{q}}, \alpha) = \frac{\frac{1}{2}a^{2}}{\Delta\sigma\Delta\theta}$$

$$= \frac{1}{2\Delta\sigma\Delta\theta} \sum_{n=1}^{N} \sum_{m=1}^{N} w_{n}(\alpha) w_{m}^{*}(\alpha) \frac{4}{R^{2}} X_{\mathbf{q}}(\mathbf{x}_{n}, \mathbf{y}_{n}) X_{\mathbf{q}}^{*}(\mathbf{x}_{m}, \mathbf{y}_{m})$$

$$= \frac{1}{\Delta\theta} \sum_{n=1}^{N} \sum_{m=1}^{N} w_{n}(\alpha) w_{m}^{*}(\alpha) \left[ \frac{2}{R^{2}\Delta\sigma} X_{\mathbf{q}}(\mathbf{x}_{n}, \mathbf{y}_{n}) X_{\mathbf{q}}^{*}(\mathbf{x}_{m}, \mathbf{y}_{m}) \right]$$
(C22)

where the hat (^) means an estimate, and terms in the last equality have simply been regrouped.

12. The bracketed term in Equation C22 is a conventional discrete frequency cross-spectrum, denoted  $E_{\rm em}(\sigma_{\rm q})$  and identically equal to  $C_{\rm em}(\sigma_{\rm q})$  -  $iQ_{\rm em}(\sigma_{\rm q})$ , as described by Bendat and Piersol (1971). Within the brackets, the first Fourier transform term  $X_{\rm q}(x_{\rm n},y_{\rm n})$  is from a time series collected from gage n of the array. The second Fourier transform term  $X_{\rm q}^{*}(x_{\rm m},y_{\rm m})$  is the conjugate of the transform of a time series collected from gage m, which is generally different from gage n. The frequency increment  $\Delta\sigma$  is known from conventional discrete Fourier transformation to be  $\Delta\sigma=2\pi/R\Delta\tau$ . With these substitutions, the bracketed term in Equation C22 becomes

$$\frac{2}{R^2 \Delta \sigma} X_q(x_n, y_n) X_q^*(x_m, y_m) = E_{mm}(\sigma_q)$$

$$= C_{mm}(\sigma_q) - i Q_{mm}(\sigma_q)$$
(C23)

and the estimate  $\hat{E}(\sigma_q, a)$  becomes

$$\hat{E}(\sigma_{\mathbf{q}}, \alpha) = \frac{1}{\Delta \theta} \sum_{n=1}^{N} \sum_{m=1}^{N} w_{n}(\alpha) w_{n}^{*}(\alpha) \left[ C_{mn}(\sigma_{\mathbf{q}}) - i Q_{mn}(\sigma_{\mathbf{q}}) \right]$$
 (C24)

- 13. It is important to note at this point that a variance density estimate has been formulated from a basic Fourier transform definition and a more reliable estimate must be formed to avoid arithmetic problems later. Cross-spectral estimates formed from raw Fourier transforms have broad confidence intervals, i.e., alone they have rather high uncertainty. Confidence is improved by obtaining long time series, segmenting records before transformation, computing cross-spectral estimates for corresponding pairs of segments, and averaging segment estimates together. Further reliability is obtained when estimates from adjacent frequency bands are also averaged together. The trade-off is that the final resolution frequency bandwidth is broader than for the raw estimates. However, sampling strategies can usually keep the new bandwidth tolerably narrow. These smoothing methods are standard procedures in spectral estimation. The point here is that it is essential for smoothed estimates to be used in maximum likelihood estimation.
- 14. In this derivation, smoothing can take place as soon as products of Fourier transforms are formed. Hence, one can smooth any of Equations C21 to C24, under the assumption that the weights  $w(\alpha)$  are not affected by this process. If only segment averaging is done, the meaning of the notation in

the rest of this derivation is unchanged. If band averaging is done, subsums of terms will be computed over small ranges of the subscript  $\,\mathbf{q}\,$  and the normalizing bandwidth  $\,\Delta\sigma\,$  will be larger (equal to the number of bands averaged times the raw bandwidth  $\,2\pi/\mathrm{R}\Delta\tau$ ). If, for the remainder of this derivation, subscript  $\,\mathbf{q}\,$  is considered to be the index of this new set of frequency bands, then the notation need not be changed.

- 15. A logical next step is to define  $\Delta\theta$ , but this is difficult to do at this stage. Hypothetically, the method seeks a single wave train having a single propagation direction  $\alpha$  . Under ideal conditions, the arc of direction in the frequency-direction domain represented by this wave train is of zero width, i.e., the spectrum is a spike or delta function at direction  $\alpha$ . However, directional resolving ability is limited by the number of observations available, so there is a finite arc width associated with the fitted wave train, just as there is a finite bandwidth in the frequency domain. Because of the intricate arithmetic and dependence on the number and separation of gages, it is usually not possible to assign a resolution arc width until the estimator is completely derived. At that time, a resolution arc width can be found empirically by examining the minimum angular separation of two wave trains that can, by some criterion, be distinguished with the estimator. This procedure is usually done with artificial wave signals, solving the estimator equations for a large number of individual look directions (a's) and then deciding how small an arc is required for estimates from adjacent look directions to be reasonably statistically independent. Results will be a function of frequency (long waves are more difficult to resolve) and may be a function of direction, depending on the geometry of the gage array.
- 16. Given that, for now,  $\Delta\theta$  is not defined, the working entity is the frequency-direction spectrum times an unspecified arc width. Hence, multiplying both sides of Equation C24 by  $\Delta\theta$  results in what is essentially the qth element of a slice of a direction-bounded frequency spectrum of arc width  $\Delta\theta$  centered along look direction  $\alpha$ , or

$$\hat{E}(\sigma_{\mathbf{q}}, \alpha) \Delta \theta = \sum_{n=1}^{N} \sum_{m=1}^{N} w_{n}(\alpha) w_{m}^{*}(\alpha) \left[ C_{mn}(\sigma_{\mathbf{q}}) - i Q_{mn}(\sigma_{\mathbf{q}}) \right]$$

$$= \sum_{n=1}^{N} \sum_{m=1}^{N} w_{n}(\alpha) w_{m}^{*}(\alpha) E_{mn}(\sigma_{\mathbf{q}})$$
(C25)

The model is a weighted sum of the frequency cross-spectra of sea surface displacement at frequency  $\sigma_q$  between all possible pairs of gages n and m, where the weights are unique to the single direction  $\alpha$ . Weights are determined based on reasoning derived from consideration of ideal spectra.

17. Complete, ideal cross-spectra are related to the true frequency-direction spectrum  $E(\sigma,\theta)$  (no hat) by Equation Cl2. If this expression is adapted to an array of gages positioned arbitrarily (for now) in x,y coordinates, separations between gages m and n are

$$X = x_n - x_n$$

$$Y = y_n - y_n$$
(C26)

Use of Equations C26 in Equation C12 gives an expression for cross-spectra of sea surface displacement in terms of gage separation

$$C_{mn}(\sigma_q) - iQ_{mn}(\sigma_q) = C(x_m - x_n, y_m - y_n, \sigma_q) - iQ(x_m - x_n, y_m - y_n, \sigma_q)$$

$$= \int_0^{2\pi} E(\sigma_q, \theta) e^{-ik_q[(x_m - x_n)\cos\theta + (y_m - y_n)\sin\theta]} d\theta$$
(C27)

18. The next step is to isolate that part of the spectrum near look direction  $\alpha$ . This is done by asserting that the total directional spectrum at frequency  $\sigma_q$  is made up of two parts: a spike or delta function at the look direction  $\alpha$  that represents a single, signal-containing wave train, and a "noise" spectrum that represents some true noise, but also the rest of the true spectrum that is to have minimum influence on the estimate at look direction  $\alpha$ . That is, a kind of filter is enforced that only allows information near look direction  $\alpha$ . The two parts of  $E(\sigma_q, \theta)$  can be written

$$E(\sigma_{\mathbf{q}}, \theta) = H(\theta - \alpha, \Delta \theta) E(\sigma_{\mathbf{q}}, \alpha) + E_{\mathbf{R}}(\sigma_{\mathbf{q}}, \theta)$$
 (C28)

where  $E(\sigma_q,\alpha)$  is the desired piece of the total spectrum,  $E_R(\sigma_q,\theta)$  is the rest of the spectrum the influence of which is to be minimized, and  $H(\theta-\alpha,\Delta\theta)$  is an isolating function. The isolating function has a value of 1 in a region  $\Delta\theta$  wide about direction  $\alpha$  and is zero elsewhere. Its effect is to allow an artificial distribution of the energy in the spike of  $E(\sigma_q,\alpha)$  over a finite arc width  $\Delta\theta$ .

19. If Equation C28 is substituted into the integral of Equation C27, one obtains

$$\begin{split} C_{\text{mm}}(\sigma_{\mathbf{q}}) &= \int_{0}^{2\pi} \left[ H(\theta - \alpha, \Delta \theta) \, E(\sigma_{\mathbf{q}}, \alpha) \, + E_{\mathbf{g}}(\sigma_{\mathbf{q}}, \theta) \right] e^{-ik_{\mathbf{q}} \left[\cos\theta \, (\mathbf{x}_{\mathbf{n}} - \mathbf{x}_{\mathbf{n}}) \, + \, \sin\theta \, (\mathbf{y}_{\mathbf{n}} - \mathbf{y}_{\mathbf{n}}) \right]} \, d\theta \\ &= \int_{0}^{2\pi} H(\theta - \alpha, \Delta \theta) \, E(\sigma_{\mathbf{q}}, \alpha) \, e^{-ik_{\mathbf{q}} \left[\cos\theta \, (\mathbf{x}_{\mathbf{n}} - \mathbf{x}_{\mathbf{n}}) \, + \, \sin\theta \, (\mathbf{y}_{\mathbf{n}} - \mathbf{y}_{\mathbf{n}}) \right]} \, d\theta \\ &\quad + \int_{0}^{2\pi} E_{\mathbf{g}}(\sigma_{\mathbf{q}}, \theta) \, e^{-ik_{\mathbf{q}} \left[\cos\theta \, (\mathbf{x}_{\mathbf{n}} - \mathbf{x}_{\mathbf{n}}) \, + \, \sin\theta \, (\mathbf{y}_{\mathbf{n}} - \mathbf{y}_{\mathbf{n}}) \right]} \, d\theta \\ &= E(\sigma_{\mathbf{q}}, \alpha) \int_{0}^{2\pi} H(\theta - \alpha, \Delta \theta) \, e^{-ik_{\mathbf{q}} \left[\cos\theta \, (\mathbf{x}_{\mathbf{n}} - \mathbf{x}_{\mathbf{n}}) \, + \, \sin\theta \, (\mathbf{y}_{\mathbf{n}} - \mathbf{y}_{\mathbf{n}}) \right]} \, d\theta \\ &\quad + \int_{0}^{2\pi} E_{\mathbf{g}}(\sigma_{\mathbf{q}}, \theta) \, e^{-ik_{\mathbf{q}} \left[\cos\theta \, (\mathbf{x}_{\mathbf{n}} - \mathbf{x}_{\mathbf{n}}) \, + \, \sin\theta \, (\mathbf{y}_{\mathbf{n}} - \mathbf{y}_{\mathbf{n}}) \right]} \, d\theta \end{split}$$

Some effort is required to evaluate the first integral on the right side of the last equality. The function  $H(\theta-\alpha,\Delta\theta)$  has the simple effect of resetting the limits on the integral so that one can write

$$\int_{0}^{2\pi} H(\theta - \alpha, \Delta \theta) e^{-ik_{q}[\cos\theta (x_{m} - x_{n}) + \sin\theta (y_{m} - y_{n})]} d\theta$$

$$= \int_{\alpha - \frac{1}{2}\Delta \theta}^{\alpha + \frac{1}{2}\Delta \theta} e^{-ik_{q}[\cos\theta (x_{m} - x_{n}) + \sin\theta (y_{m} - y_{n})]} d\theta$$
(C30)

The integrand can be expanded as infinite sums of the products of Bessel functions of the gage separations and sinusoidal functions of  $\theta$ . The sinusoids can be integrated and, if  $\Delta\theta$  is small enough, results can be expressed as products of  $\Delta\theta$  and sinusoids of  $\alpha$ . The infinite sums of the resulting products of Bessel functions of the gage separations and sinusoidal functions of  $\alpha$  can then be contracted to an exponential function. Equation C30 then becomes the approximate expression

$$\int_{\alpha-1\Delta\theta}^{\alpha+\frac{1}{2}\Delta\theta} e^{-ik_{q}[(x_{n}-x_{n})\cos\theta + (y_{n}-y_{n})\sin\theta]} d\theta \approx e^{-ik_{q}[(x_{n}-x_{n})\cos\alpha + (y_{n}-y_{n})\cos\alpha]} \Delta\theta$$
 (C31)

The expression for the frequency cross-spectra then takes the form

$$C_{\text{men}}(\sigma_{\mathbf{q}}) - iQ_{\text{men}}(\sigma_{\mathbf{q}}) \approx E(\sigma_{\mathbf{q}}, \alpha) \Delta \theta \ e^{-i\mathbf{k}_{\mathbf{q}}[(\mathbf{x}_{\mathbf{q}} - \mathbf{x}_{\mathbf{n}})\cos\alpha + (\mathbf{y}_{\mathbf{q}} - \mathbf{y}_{\mathbf{n}})\sin\alpha]}$$

$$+ \int_{0}^{2\pi} E_{\mathbf{x}}(\sigma_{\mathbf{q}}, \theta) \ e^{-i\mathbf{k}_{\mathbf{q}}[(\mathbf{x}_{\mathbf{q}} - \mathbf{x}_{\mathbf{n}})\cos\theta + (\mathbf{y}_{\mathbf{q}} - \mathbf{y}_{\mathbf{n}})\sin\theta]} \ d\theta$$
(C32)

20. If the frequency cross-spectra of Equation C32 are substituted into the model Equation C25, one obtains

$$\begin{split} \hat{E}(\sigma_{\mathbf{q}},\alpha) \, \Delta\theta &= \sum_{n=1}^{H} \sum_{m=1}^{H} w_{n}(\alpha) \, w_{n}^{*}(\alpha) \bigg[ \, E(\sigma_{\mathbf{q}},\alpha) \, \Delta\theta \, e^{-i\mathbf{k}_{\mathbf{q}} [(\mathbf{x}_{n} - \mathbf{x}_{n})\cos\alpha + (\mathbf{y}_{n} - \mathbf{y}_{n})\sin\alpha]} \\ &\quad + \int_{0}^{2\pi} E_{\mathbf{H}}(\sigma_{\mathbf{q}},\theta) \, e^{-i\mathbf{k}_{\mathbf{q}} [(\mathbf{x}_{n} - \mathbf{x}_{n})\cos\theta + (\mathbf{y}_{n} - \mathbf{y}_{n})\sin\theta]} \, d\theta \bigg] \\ &= E(\sigma_{\mathbf{q}},\alpha) \, \Delta\theta \sum_{n=1}^{H} \sum_{m=1}^{H} w_{n}(\alpha) \, w_{n}^{*}(\alpha) \, e^{-i\mathbf{k}_{\mathbf{q}} [(\mathbf{x}_{n} - \mathbf{x}_{n})\cos\alpha + (\mathbf{y}_{n} - \mathbf{y}_{n})\sin\alpha]} \\ &\quad + \sum_{n=1}^{H} \sum_{m=1}^{H} w_{n}(\alpha) \, w_{n}^{*}(\alpha) \, \int_{0}^{2\pi} E_{\mathbf{H}}(\sigma_{\mathbf{q}},\theta) \, e^{-i\mathbf{k}_{\mathbf{q}} [(\mathbf{x}_{n} - \mathbf{x}_{n})\cos\theta + (\mathbf{y}_{n} - \mathbf{y}_{n})\sin\theta]} \, d\theta \end{split}$$

$$&= E(\sigma_{\mathbf{q}},\alpha) \, \Delta\theta \left[ \sum_{n=1}^{H} \sum_{m=1}^{H} w_{n}(\alpha) \, w_{n}^{*}(\alpha) \, e^{-i\mathbf{k}_{\mathbf{q}} [(\mathbf{x}_{n} - \mathbf{x}_{n})\cos\alpha + (\mathbf{y}_{n} - \mathbf{y}_{n})\sin\alpha]} \right] \\ &\quad + \int_{0}^{2\pi} \left[ \sum_{n=1}^{H} \sum_{m=1}^{H} w_{n}(\alpha) \, w_{n}^{*}(\alpha) \, e^{-i\mathbf{k}_{\mathbf{q}} [(\mathbf{x}_{n} - \mathbf{x}_{n})\cos\alpha + (\mathbf{y}_{n} - \mathbf{y}_{n})\sin\theta]} \right] E_{\mathbf{H}}(\sigma_{\mathbf{q}},\theta) \, d\theta \end{split}$$

In the second equality of Equation C33,  $E(\sigma_q,\alpha)\Delta\theta$  was moved outside the double sum because it does not explicitly depend on m or n. In the third equality, the double sum and weights are moved inside the integral because the computation can be done in any order. Also in the third equality, the weights and the exponential functions are bracketed together with the double summation signs, thereby grouping the summation dependent terms.

21. The bracketed terms in the last equality of Equation C33 are called window functions, the general form of which is denoted  $W(\alpha, \theta)$  and defined by

$$W(\alpha,\theta) = \sum_{n=1}^{N} \sum_{m=1}^{N} w_n(\alpha) w_m^*(\alpha) e^{-ik_q((x_m - x_n)\cos\theta + (y_m - y_n)\sin\theta)}$$
(C34)

and the special form where  $\alpha = \theta$  is

$$W(\alpha,\alpha) = \sum_{n=1}^{N} \sum_{m=1}^{N} w_n(\alpha) w_m^*(\alpha) e^{-ik_q[(x_m - x_n)\cos\alpha + (y_m - y_n)\sin\alpha]}$$
(C35)

Using the window function notation, the estimated spectrum from the last equality of Equation C33 becomes

$$\hat{E}(\sigma_{\mathbf{q}}, \alpha) \Delta \theta \approx E(\sigma_{\mathbf{q}}, \alpha) \Delta \theta W(\alpha, \alpha) + \int_{0}^{2\pi} W(\alpha, \theta) E_{\mathbf{g}}(\sigma_{\mathbf{q}}, \theta) d\theta$$
 (C36)

22. A constraint on the problem arises where there is no "noise" spectrum and the true spectrum is all that exists. That is, if  $\mathbb{E}_{\mathbb{N}}(\sigma_q,\alpha)=0$ , it is required that  $\hat{\mathbb{E}}(\sigma_q,\alpha)\Delta\theta=\mathbb{E}(\sigma_q,\alpha)\Delta\theta$ . For this expression to be true,  $\mathbb{W}(\alpha,\alpha)=1$ . Note that the expression for  $\mathbb{W}(\alpha,\alpha)$  can be factored as follows

$$\begin{split} \widetilde{W}(\alpha,\alpha) &= \sum_{n=1}^{N} \sum_{m=1}^{N} w_n(\alpha) w_m^*(\alpha) e^{-ik_q[(x_m-x_n)\cos\alpha + (y_m-y_n)\sin\alpha]} \\ &= \sum_{n=1}^{N} \sum_{m=1}^{N} w_n(\alpha) w_m^*(\alpha) e^{-ik_q(x_m\cos\alpha + y_m\sin\alpha)} e^{ik_q(x_n\cos\alpha + y_n\sin\alpha)} \\ &= \sum_{n=1}^{N} \sum_{m=1}^{N} w_n(\alpha) e^{ik_q(x_n\cos\alpha + y_n\sin\alpha)} w_m^*(\alpha) e^{-ik_q(x_m\cos\alpha + y_m\sin\alpha)} \\ &= \sum_{n=1}^{N} w_n(\alpha) e^{ik_q(x_n\cos\alpha + y_n\sin\alpha)} \sum_{m=1}^{N} w_m^*(\alpha) e^{-ik_q(x_m\cos\alpha + y_m\sin\alpha)} \\ &= \left[ \sum_{n=1}^{N} w_n(\alpha) e^{ik_q(x_n\cos\alpha + y_n\sin\alpha)} \right] \left[ \sum_{m=1}^{N} w_m(\alpha) e^{ik_q(x_m\cos\alpha + y_m\sin\alpha)} \right]^* \end{split}$$

Because the term in the second bracket of the last equality is simply the complex conjugate of the term in the first bracket, Equation C37 can be written

$$W(\alpha,\alpha) = \left| \sum_{n=1}^{N} w_n(\alpha) e^{ik_q(x_n\cos\alpha + y_n\sin\alpha)} \right|^2$$
 (C38)

and it is seen that the window is always a positive and real. The constraint that  $W(\alpha,\alpha)=1$  is satisfied (not necessarily uniquely) if

$$\sum_{n=1}^{N} w_n(\alpha) e^{ik_q(x_n\cos\alpha + y_n\sin\alpha)} = \sum_{n=1}^{N} w_n^*(\alpha) e^{-ik_q(x_n\cos\alpha + y_n\sin\alpha)} = 1$$
 (C39)

The more general window  $W(\alpha, \theta)$  can also be disassembled and rewritten as

$$W(\alpha,\theta) = \left| \sum_{n=1}^{H} w_n(\alpha) e^{ik_q(x_n\cos\theta + y_n\sin\theta)} \right|^2$$
 (C40)

and it is noted that, because it is a magnitude squared, its values are real and positive or zero for all directions  $\theta$ .

23. With  $W(\alpha,\alpha) = 1$ , our estimated spectrum from Equation C36 becomes

$$\hat{E}(\sigma_{\mathbf{q}}, \alpha) \Delta \theta \approx E(\sigma_{\mathbf{q}}, \alpha) \Delta \theta + \int_{0}^{2\pi} W(\alpha, \theta) E_{\mathbf{g}}(\sigma_{\mathbf{q}}, \theta) d\theta \qquad (C41)$$

To minimize the contribution from the "noise" spectrum, the integral in Equation C41 must be made as small as possible. It is noted that  $E(\sigma_q,\alpha)$  is of fixed value and positive, that  $W(\alpha,\theta)$  is positive by Equation C40 and that  $E_R(\sigma_q,\theta)$  is positive, so that everything on the right side of Equation C41 is positive. Making the integral as small as possible is then equivalent to making  $\hat{E}(\sigma_q,\alpha)$  as small as possible. That can be done for any expression defining  $\hat{E}(\sigma_q,\alpha)$ . Instead of minimizing Equation C41, one can minimize Equation C25, which is a more basic model definition. At the same time one must satisfy the window constraint of Equation C39.

- 24. Minimization means finding the derivatives of Equations C25 and C39 with respect to the real and imaginary parts of the complex weights  $\mathbf{w}_n$ , setting the derivatives equal to zero and solving the subsequent set of simultaneous equations for the weights. Use of these minimizing weights in the model Equation C25 yields a maximum likelihood estimate of the spectral density at frequency  $\sigma_q$  and direction  $\alpha$ . Direction binwidth  $\Delta\theta$  continues to be undefined until the minimization has been completed.
- 25. Minimization of Equations C25 and C39 at the same time entails use of a method known as Lagrange multipliers, a subject covered in most advanced calculus texts of which Hildebrand (1965) is one. To set it up, it is noted that if Equation C39 is true then

$$1 - \sum_{n=1}^{N} w_n(\alpha) e^{ik_q(x_n\cos\alpha + y_n\sin\alpha)} = 0$$
 (C42)

and Equation C42 can be added, with a coefficient, to the right side of Equation C25 without changing the truth of Equation C25 or Equation C39. This procedure gives us

$$\hat{E}(\sigma_q,\alpha) \Delta \theta = \sum_{n=1}^{H} \sum_{m=1}^{H} w_n(\alpha) w_m^*(\alpha) E_{mn}(\sigma_q) + \lambda \left[ 1 - \sum_{n=1}^{H} w_n(\alpha) e^{ik_q(x_n\cos\alpha + y_n\sin\alpha)} \right] (C43)$$

The coefficient  $\lambda$  is called a Lagrange multiplier. Upon zeroing the derivatives of Equation C43 with respect to the real and imaginary parts of the  $w_n$ , one will obtain 2N equations (N equations for the real parts and N for the imaginary parts) that will yield the  $w_n$  in terms of  $\lambda$ . If these weights are used in Equation C39, another equation is obtained that can be used to solve for  $\lambda$ .

26. To illustrate this procedure, consider an array of 3 non-collinear wave gages. The analysis will work with any larger number of gages, but the bookkeeping takes longer to write. By showing the derivation for a 3-gage array, one can see the generalization for a larger array. With 3 gages, there are ( N = ) 3 time series, so that for each frequency  $\sigma_{\rm q}$ , there are 3 Fourier coefficients and three weights  $w_{\rm n}$  to find. Each weight is complex. The real and imaginary parts of the weights are identified by defining

$$\mathbf{w}_{\mathbf{n}} = \mathbf{w}_{\mathbf{n}\mathbf{R}} + \mathbf{i}\mathbf{w}_{\mathbf{n}\mathbf{I}} \tag{C44}$$

and its complex conjugate

$$\mathbf{w}_{\mathbf{n}}^{\bullet} = \mathbf{w}_{\mathbf{n}\mathbf{R}} - i\mathbf{w}_{\mathbf{n}\mathbf{I}} \tag{C45}$$

Products of weights as they appear in Equation C43 take the form

$$w_{n}w_{m}^{*} = (w_{nR} + iw_{nI})(w_{mR} - iw_{mI})$$

$$= (w_{nR}w_{mR} + w_{nI}w_{mI}) + i(w_{nI}w_{mR} - w_{nR}w_{mI})$$
(C46)

To save space, the parentheses and the independent variables they carried have been dropped for now. They will be replaced at the end of the derivation.

27. The six differentiations required to minimize Equation C43 can be written as

$$\frac{\partial}{\partial w_{nB}} \hat{E}(\sigma_{q}, \alpha) \Delta \theta = \frac{\partial}{\partial w_{nI}} \hat{E}(\sigma_{q}, \alpha) \Delta \theta = 0 \qquad n = 1, 2, 3$$
 (C47)

or, using the right side of Equation C43 and expanding the differentials,

$$\frac{\partial}{\partial w_{1R}} = \frac{\partial}{\partial w_{2R}} = \frac{\partial}{\partial w_{3R}} = \frac{\partial}{\partial w_{3R}} = \frac{\partial}{\partial w_{1I}} = \frac{\partial}{\partial w_{2I}} = \frac{\partial}{\partial w_{2I}} = \frac{\partial}{\partial w_{3I}} = \frac{\partial$$

where the terms in the curly brackets expand to

$$(w_{1R}^{2} + w_{1I}^{2})E_{11} + [(w_{1R}w_{2R} + w_{1I}w_{2I}) + i(w_{1I}w_{2R} - w_{1R}w_{2I})]E_{21}$$

$$+ [(w_{1R}w_{3R} + w_{1I}w_{3I}) + i(w_{1I}w_{3R} - w_{1R}w_{3I})]E_{31}$$

$$+ [(w_{2R}w_{1R} + w_{2I}w_{1I}) + i(w_{2I}w_{1R} - w_{2R}w_{1I})]E_{12}$$

$$+ (w_{2R}^{2} + w_{2I}^{2})E_{22} + [(w_{2R}w_{3R} + w_{2I}w_{3I}) + i(w_{2I}w_{3R} - w_{2R}w_{3I})]E_{32}$$

$$+ [(w_{3R}w_{1R} + w_{3I}w_{1I}) + i(w_{3I}w_{1R} - w_{3R}w_{1I})]E_{13}$$

$$+ [(w_{3R}w_{2R} + w_{3I}w_{2I}) + i(w_{3I}w_{2R} - w_{3R}w_{2I})]E_{23} + (w_{3R}^{2} + w_{3I}^{2})E_{33}$$

$$+ \lambda \Big[1 - (w_{1R} + iw_{1I})e^{ik_{q}(x_{1}\cos\alpha + y_{1}\sin\alpha)} - (w_{2R} + iw_{2I})e^{ik_{q}(x_{2}\cos\alpha + y_{2}\sin\alpha)} - (w_{3R} + iw_{3I})e^{ik_{q}(x_{3}\cos\alpha + y_{3}\sin\alpha)}\Big]$$

Taking the partial differential of Expression C48 with respect to  $w_{1R}$  and setting it equal to zero yields

$$2w_{1R}E_{11} + (w_{2R}-iw_{21})E_{21} + (w_{3R}-iw_{31})E_{31} + (w_{2R}+iw_{21})E_{12} + (w_{3R}+iw_{31})E_{13} - \lambda e^{ik_{q}(x,\cos\alpha + y,\sin\alpha)} = 0$$
(C50)

Similarly the partials with respect to  $w_{ZR}$  and  $w_{3R}$  lead, respectively, to

$$(w_{1R} + iw_{1I})E_{21} + (w_{1R} - iw_{1I})E_{12} + 2w_{2R}E_{22} + (w_{3R} - iw_{3I})E_{32}$$

$$+ (w_{3R} + iw_{3I})E_{23} - \lambda e^{ik_q(x_2\cos\alpha + y_2\sin\alpha)} = 0$$
(C51)

$$(w_{1R} + iw_{1I})E_{31} + (w_{2R} + iw_{2I})E_{32} + (w_{1R} - iw_{1I})E_{13} + (w_{2R} - iw_{2I})E_{23}$$

$$+ 2w_{3R} - \lambda e^{ik_q(x_3\cos\alpha + y_3\sin\alpha)} = 0$$
(C52)

The partials with respect to  $w_{1I}$ ,  $w_{2I}$  and  $w_{3I}$  yield, respectively,

$$2w_{11}E_{11} + (w_{21}+iw_{2R})E_{21} + (w_{31}+iw_{3R})E_{31} + (w_{21}-iw_{2R})E_{12}$$

$$+ (w_{31}-iw_{3R})E_{13} - i\lambda e^{ik_{q}(x_{1}\cos q + y_{1}\sin q)} = 0$$
(C53)

$$(w_{11} - iw_{1R}) E_{21} + (w_{11} + iw_{1R}) E_{12} + 2w_{21} E_{22} + (w_{31} + iw_{3R}) E_{32}$$

$$+ (w_{31} - iw_{3R}) E_{23} - i\lambda e^{ik_q(x_2\cos\alpha + y_2\sin\alpha)} = 0$$

$$(C54)$$

$$(w_{1I} - iw_{1R}) E_{31} + (w_{2I} - iw_{2R}) E_{32} + (w_{1I} + iw_{1R}) E_{13} + (w_{2I} + iw_{2R}) E_{23}$$

$$+ 2w_{3I} E_{33} - i\lambda e^{ik_q(x_3 \cos \alpha + y_3 \sin \alpha)} = 0$$
(C55)

Equations C50, C51 and C52 can be written in more abbreviated form by using the definitions of Equations C44 and C45. If terms containing  $\lambda$  are also moved to the right sides of the equations, one obtains

$$2w_{1R}E_{11} + w_2^*E_{21} + w_3^*E_{31} + w_2E_{12} + w_3E_{13} = \lambda e^{ik_q(x_1\cos\alpha + y_1\sin\alpha)}$$
 (C56)

$$w_1 E_{21} + w_1^* E_{12} + 2w_{22} E_{22} + w_3^* E_{32} + w_3 E_{23} = \lambda e^{ik_q(x_2\cos\alpha + y_2\sin\alpha)}$$
 (C57)

$$w_1 E_{31} + w_1 E_{32} + w_1^* E_{13} + w_2^* E_{23} + 2w_{3R} E_{33} = \lambda e^{ik_q(x_3 \cos \alpha + y_3 \sin \alpha)}$$
 (C58)

If Equation C53 is multiplied by i and terms are rearranged, the following sequence is induced

$$\begin{aligned} 2iw_{11}E_{11} + i(w_{21}+iw_{2R})E_{21} + i(w_{31}+iw_{3R})E_{31} \\ &+ i(w_{21}-iw_{2R})E_{12} + i(w_{31}-iw_{3R})E_{13} - i^{2}\lambda e^{ik_{q}(x_{1}\cos\alpha + y_{1}\sin\alpha)} \\ &= 2iw_{11}E_{11} + (iw_{21}-w_{2R})E_{21} + (iw_{31}-w_{3R})E_{31} \\ &+ (iw_{21}+w_{2R})E_{12} + (iw_{31}+w_{3R})E_{13} + \lambda e^{ik_{q}(x_{1}\cos\alpha + y_{1}\sin\alpha)} \end{aligned} \tag{C59}$$

$$= 2iw_{11}E_{11} - (w_{2R}-iw_{21})E_{21} - (w_{3R}-iw_{31})E_{31} \\ &+ (w_{2R}+iw_{21})E_{12} + (w_{3R}+iw_{31})E_{13} + \lambda e^{ik_{q}(x_{1}\cos\alpha + y_{1}\sin\alpha)} \end{aligned}$$

Writing Equation C59 in abbreviated form (using Equations C44 and C45) and putting the term containing  $\lambda$  on the right side results in

$$2iw_{11}E_{11} - w_2^*E_{21} - w_3^*E_{31} + w_2E_{12} + w_3E_{13} = -\lambda e^{ik_0(x_1\cos\alpha + y_1\sin\alpha)}$$
 (C60)

The same set of operations applied to Equations C54 and C55 provides, respectively,

$$w_1 E_{21} - w_1^* E_{12} + 2i w_{21} E_{22} - w_3^* E_{32} + w_3 E_{23} = -\lambda e^{i k_q (x_2 \cos \alpha + y_2 \sin \alpha)}$$
 (C61)

$$w_1 E_{31} + w_2 E_{32} - w_1^* E_{13} - W_2^* E_{23} + 2i w_{31} E_{33} = -\lambda e^{i k_q (x_3 \cos \alpha + y_3 \sin \alpha)}$$
 (C62)

If Equation C60 is subtracted from Equation C56, there results

$$(2w_{1p} - 2iw_{1})E_{11} + 2w_{2}^{*}E_{21} + 2w_{3}^{*}E_{31} = 2\lambda e^{ik_{q}(x_{1}\cos x + y_{1}\sin x)}$$
 (C63)

or, upon putting the first term on the left in simplified form and dividing by 2,

$$w_1^* E_{11} + w_2^* E_{21} + w_3^* E_{31} = \lambda e^{ik_q(x_1 \cos q + y_1 \sin q)}$$
 (C64)

Similarly, subtracting Equation C61 from Equation C57 leads to

$$w_1^* E_{12} + w_2^* E_{22} + w_3^* E_{32} = \lambda e^{ik_q(z_1 \cos \alpha + y_2 \sin \alpha)}$$
 (C65)

and Equation C62 taken from Equation C58 yields

$$w_1^* E_{13} + w_2^* E_{23} + w_3^* E_{33} = \lambda e^{ik_q(x_3 \cos x + y_3 \sin x)}$$
 (C66)

Equations C64, C65 and C66 are very similar in form and the left side of each can be written as a sum. On doing this, the equation set is expressed

$$\sum_{n=1}^{3} w_n^* E_{nn} = \lambda e^{ik_q(x_n \cos \alpha + y_n \sin \alpha)} \qquad \text{for } n = 1, 2, 3$$
 (C67)

If one multiplies Equation C64 by  $w_1$ , Equation C65 by  $w_2$  and Equation C66 by  $w_3$ , there is obtained a new set of equations that can be expressed in the summation form of Equation C67 as the product of both sides with  $w_n$ , i.e.,

$$w_{n} \sum_{m=1}^{3} w_{m}^{*} E_{mn} = w_{n} \lambda e^{ik_{q}(x_{n}\cos\alpha + y_{n}\sin\alpha)} \qquad \text{for } n = 1, 2, 3$$
 (C68)

or, upon moving w, inside the sum because the sum is only over index m,

$$\sum_{m=1}^{3} w_{n} w_{m}^{*} E_{mn} = \lambda w_{n} e^{ik_{q}(x_{n}\cos\alpha + y_{n}\sin\alpha)} \qquad \text{for } n = 1, 2, 3$$
 (C69)

If all three equations are now added together, a very simple and useful result is obtained. Adding the equations in the summation expression is the same as taking the sum over index n of both sides of Equation C69, or

The double sum on the left side of Equation C70 is recognized as the estimate of the frequency-direction spectrum defined in Equation C25. The sum on the right side of Equation C70 is identified as satisfying the window constraint expressed by Equation C39 so that the sum can be replaced by 1. Equation C70 reduces to the simple expression

$$\hat{E}(\sigma_{\alpha}, \alpha) \Delta \theta = \lambda \tag{C71}$$

Hence, if  $\lambda$  can be found, the estimator will be complete. Note that while the number of gages has been limited to 3 to keep the bookkeeping simple, all operations so far have been linear. Extension of this derivation to more gages is straightforward, consisting mostly of changing the upper limit on the summations. This derivation will continue to assume 3 gages, again for bookkeeping simplicity, but the result is more general.

28. To find  $\lambda$ , it is noted that Equations C64, C65 and C66 form a set of simultaneous equations in the conjugates of the weights  $w_n$ . These equations can be written in matrix form as

$$\begin{bmatrix}
E_{11} & E_{21} & E_{31} \\
E_{12} & E_{22} & E_{32} \\
E_{13} & E_{23} & E_{33}
\end{bmatrix}
\begin{bmatrix}
w_1^* \\
w_2^* \\
w_3^*
\end{bmatrix}
\approx \lambda
\begin{bmatrix}
e^{ik_q(\mathbf{x}_1\cos\alpha + \mathbf{y}_1\sin\alpha)} \\
e^{ik_q(\mathbf{x}_2\cos\alpha + \mathbf{y}_2\sin\alpha)} \\
e^{ik_q(\mathbf{x}_3\cos\alpha + \mathbf{y}_3\sin\alpha)}
\end{bmatrix}$$
(C72)

To find the weights, both sides of Equation C72 must be multiplied by the inverse of the matrix  $E_{ma}$ . This inverse is computed by following any recipe for matrix inversion. On finding the inverse and doing the multiplication, Equation C72 becomes

$$\begin{bmatrix} w_1^* \\ w_2^* \\ w_3^* \end{bmatrix} = \lambda \begin{bmatrix} E_{11}^{-1} & E_{21}^{-1} & E_{31}^{-1} \\ E_{12}^{-1} & E_{22}^{-1} & E_{32}^{-1} \\ E_{13}^{-1} & E_{23}^{-1} & E_{33}^{-1} \end{bmatrix} \begin{bmatrix} e^{ik_q(x_1\cos\alpha + y_1\sin\alpha)} \\ e^{ik_q(x_2\cos\alpha + y_2\sin\alpha)} \\ e^{ik_q(x_3\cos\alpha + y_3\sin\alpha)} \end{bmatrix}$$
(C73)

which can be written as individual equations by doing the matrix multiplication to form

$$w_1^* = \lambda \left[ E_{11}^{-1} e^{ik_q(x_1\cos\alpha + y_1\sin\alpha)} + E_{21}^{-1} e^{ik_q(x_2\cos\alpha + y_2\sin\alpha)} + E_{31}^{-1} e^{ik_q(x_3\cos\alpha + y_3\sin\alpha)} \right]$$
 (C74)

$$w_2^* = \lambda \left[ E_{12}^{-1} e^{ik_q(x_1 \cos \alpha + y_1 \sin \alpha)} + E_{22}^{-1} e^{ik_q(x_2 \cos \alpha + y_2 \sin \alpha)} + E_{32}^{-1} e^{ik_q(x_3 \cos \alpha + y_3 \sin \alpha)} \right]$$
 (C75)

$$w_3^* = \lambda \left[ E_{13}^{-1} e^{ik_q(x_1\cos\alpha + y_1\sin\alpha)} + E_{23}^{-1} e^{ik_q(x_2\cos\alpha + y_2\sin\alpha)} + E_{33}^{-1} e^{ik_q(x_3\cos\alpha + y_3\sin\alpha)} \right]$$
(C76)

Equations C74, C75 and C76 are of forms involving sums of similar terms. They can be compressed into a single summation equation that looks like

$$w_n^* = \lambda \sum_{m=1}^{3} E_{mn}^{-1} e^{ik_q(x_n \cos x + y_n \sin x)}$$
 for  $n = 1, 2, 3$  (C77)

This expression is readily manipulated to isolate  $\lambda$ . If both sides of Equation C77 are multiplied by  $e^{ikq(x_n\cos\alpha + y_n\sin\alpha)}$ , there results

$$w_n^* e^{-ik_q(x_n\cos\alpha + y_n\sin\alpha)} = e^{-ik_q(x_n\cos\alpha + y_n\sin\alpha)} \lambda \sum_{m=1}^3 E_{mn}^{-1} e^{ik_q(x_n\cos\alpha + y_n\sin\alpha)}$$

$$= \lambda \sum_{m=1}^3 E_{mn}^{-1} e^{ik_q(x_n\cos\alpha + y_n\sin\alpha)} e^{-ik_q(x_n\cos\alpha + y_n\sin\alpha)}$$

$$= \lambda \sum_{m=1}^3 E_{mn}^{-1} e^{ik_q((x_n\cos\alpha + y_n\sin\alpha) + (y_n-y_n)\sin\alpha)}$$
for  $n = 1, 2, 3$ 

where the exponential multiplier can go inside the summation because the sum is only over index m, and the exponents are combined in the last equality. If the 3 equations represented by Equation C78 are added together, i.e., summed on both sides over index n, the result is

$$\sum_{n=1}^{3} w_{n}^{*} e^{-ik_{q}(x_{n}\cos\alpha + y_{n}\sin\alpha)} = \sum_{n=1}^{3} \lambda \sum_{m=1}^{3} E_{mn}^{-1} e^{ik_{q}((x_{m}-x_{n})\cos\alpha + (y_{m}-y_{n})\sin\alpha)}$$

$$= \lambda \sum_{n=1}^{3} \sum_{m=1}^{3} E_{mn}^{-1} e^{ik_{q}((x_{m}-x_{n})\cos\alpha + (y_{m}-y_{n})\sin\alpha)}$$
(C79)

The left side of Equation C79 satisfies the window constraint of Equation C39 so that it equals 1 . This result leaves

$$1 = \lambda \sum_{n=1}^{3} \sum_{n=1}^{3} E_{nn}^{-1} e^{ik_{q}[(x_{n}-x_{n})\cos\alpha + (y_{n}-y_{n})\sin\alpha]}$$
 (C80)

or

$$\lambda = \frac{1}{\sum_{n=1}^{3} \sum_{m=1}^{3} E_{mn}^{-1} e^{ik_{q}[(x_{m}-x_{n})\cos\alpha + (y_{m}-y_{n})\sin\alpha]}}$$
(C81)

Hence, an expression for  $\lambda$  has been found, and, by virtue of Equation C71, so has an estimate of the frequency-direction spectrum, i.e.,

$$\hat{E}(\sigma_{\mathbf{q}}, \alpha) \Delta \theta = \frac{1}{\sum_{\mathbf{n}=1}^{3} \sum_{\mathbf{m}=1}^{3} E_{\mathbf{m}}^{-1} e^{i\mathbf{k}_{\mathbf{q}}((\mathbf{x}_{\mathbf{n}} - \mathbf{x}_{\mathbf{n}})\cos\alpha + (\mathbf{y}_{\mathbf{n}} - \mathbf{y}_{\mathbf{n}})\sin\alpha)}}$$
(C82)

This is the result being sought, a maximum likelihood estimate of the wave variance per frequency increment at frequency  $\sigma_q$  and look direction  $\alpha$ .

29. The angle increment  $\Delta\theta$  still has not been defined, however. This definition can be found, symbolically at least, by noting that, in practice, Equation C82 is commonly solved for a number of evenly spaced, discrete lock angles  $\theta_r$  defined by

$$\theta_r = r\Delta\theta$$
 for  $r = 1, 2, ..., R$  (C83)

such that, for the 360 degrees or  $2\pi$  radians of arc that can be examined with a two-dimensional array,

$$\theta_{R} = R\Delta\theta = 2\pi \tag{C84}$$

from which  $\Delta\theta=2\pi/R$ . With this definition of  $\Delta\theta$  and the set of discrete directions given by Equation C83, the frequency-direction spectral estimate at frequency  $\sigma_{\alpha}$  and direction  $\theta_{r}$  is

$$\hat{E}(\sigma_{q}, \theta_{r}) = \frac{1}{\frac{2\pi}{R} \sum_{n=1}^{3} \sum_{m=1}^{3} E_{mm}^{-1} e^{ik_{q}[(x_{n}-x_{n})\cos\theta_{r} + (y_{n}-y_{n})\sin\theta_{r}]}}$$
(C85)

Again, nothing has been done in this derivation that precludes adding more gages to the array. Discussion was limited to three gages, mostly so the equation sets and matrix inversion equations would fit into a reasonable amount of space. Extension of the result given by Equation C85 is achieved symbolically by simply changing the upper limits on the sums, so a more general result is

$$\hat{E}(\sigma_{\mathbf{q}}, \theta_{\mathbf{z}}) = \frac{1}{\frac{2\pi}{R} \sum_{n=1}^{K} \sum_{m=1}^{K} E_{mn}^{-1} e^{i\mathbf{k}_{\mathbf{q}}[(\mathbf{x}_{\mathbf{n}} - \mathbf{x}_{\mathbf{n}})\cos\theta_{\mathbf{r}} + (\mathbf{y}_{\mathbf{n}} - \mathbf{y}_{\mathbf{n}})\sin\theta_{\mathbf{r}}]}}$$
(C86)

where N is the number of gages, as before.

- 30. One must still do some empirical work to pin down  $\Delta\theta$  (or R), because the directional resolution of the estimator depends very strongly on both the array design and the nature of the true spectrum that governs the data collected with the set of gages. One should use synthetic data, for which the true spectrum is known, to examine the response of a particular array design. From such results, one can determine the extent to which the array can resolve various wave approach directions, including cases where waves come from several directions at the same frequency. Some very good guidance on proper placement of gages in array design is given by Davis and Regier (1977).
- 31. Once an array is designed and deployed such that data are obtained, one applies this method by computing the cross-spectra between all gage pairs, forming the cross-spectral matrix  $\mathbf{E}_{\mathbf{m}}$  for each frequency  $\sigma_{\mathbf{q}}$ , computing the inverse of the cross-spectral matrix, and applying the estimator Equation C86 for each discrete direction  $\theta_{\mathbf{r}}$ .
- 32. This method is not constrained to conserve total variance, so when the frequency-direction spectral estimates are integrated with respect to direction, the frequency spectrum is not necessarily recovered completely. There are two common ways to deal with this. The simplest one is to perform the integration with respect to direction at frequency  $\sigma_{\alpha}$  , compute the ratio of the variance from the frequency spectrum to the result of the integration, and multiply all values of the frequency-direction spectrum at this frequency by the computed ratio. This form of correction distributes the error as a uniform percentage over the entire directional distribution. A second correction method, known as Iterativ. Maximum Likelihood Estimation, is based on a method derived by Pawka (1983). The reasoning of Pawka's method is that if the MLE result is fed back into the estimation algorithm, the result of the second pass tends to be an attenuated form of the first pass. If results from the first pass are multiplied, direction-by-direction, by the ratio of first pass results to second pass results, the new estimate tends to be closer to the true spectrum than the first pass results. Extensive empirical tests by

Pawka indicate that repeated application of this procedure tends to produce an estimator that is much better than the single-pass M.E. not only giving better fidelity to the total variance, but also sharpening resolution in the detailed structure of the directional distribution of variance. The mathematics of this procedure are not discussed here because they are rather well described by Pawka (1983) and by Oltman-Shay and Guza (1984).

33. Thus, this appendix has outlined some of the reasoning and some of the mathematical detail of maximum likelihood estimation of wave directionality when used with a two-dimensional array. Equation C86 was used identically to estimate the frequency-direction spectra discussed in the body of this report.

Appendix D: Notation

## Appendix D: Notation

[]* Complex conjugate of [ ] Wave amplitude Amplitude of nth component wave a_n Duration of time Fourier series cosine coefficient at qth frequency Aa Span along x-direction В Fourier series sine coefficient at qth frequency Ba Span along y-direction C Coincident spectral density between gages m and n C_ Water depth đ Mnemonic for two-digit day of the month dd Complex wave amplitude D Element of directional distribution function at nth  $D(f_n, \theta_m)$ frequency and mth direction Complex amplitude of nth component wave  $D_n$ E Frequency-direction spectral density Estimate of frequency-direction spectral density Ê E Cross-spectral density between gages m and n Element of row m and column n of matrix inverse of E-1 Noise component of frequency-direction spectrum E £ Cyclic frequency Cyclic frequency of nth component wave f, Spectral peak frequency f, Peak frequency of incident spectrum  $f_{p,1}$ Peak frequency of reflected spectrum  $f_{p,z}$ 

- g Gravitational acceleration
- H Isolating function
- H_ Spectrum-based characteristic wave height
- $H_{mo.i}$  Characteristic height of incident spectrum
- $H_{mo,r}$  Characteristic height of reflected spectrum
  - k Radian wavenumber
  - k, Wavenumber of nth component wave
  - m Index integer
  - mm Mnemonic for two-digit representation of month in a calender year
  - M Upper limit of indices denoted m
  - n Index integer
  - N Upper limit of indices denoted n
  - q Index integer
  - Q Quadrature spectral density
  - Q Quadrature spectral density between gages m and n
    - r Index integer
    - R Upper limit of indices denoted r Covariance function
    - S Spectral density
- S(f) Frequency spectral density
- S(f_n) Frequency spectral density at nth discrete frequency
- $S(f_n, \theta_m)$  Frequency-direction spectral density at  $n^{th}$  discrete frequency and  $m^{th}$  discrete direction
  - $S(\theta)$  Direction spectral density
  - $S_i(f_n)$  Incident frequency spectral density at  $n^{th}$  discrete frequency
  - $S_r(f_n)$  Reflected frequency spectral density at  $n^{th}$  discrete frequency
    - t Time

- T Arbitrary displacement in time
- T_p Spectral peak period
- T_{n.i} Peak period of incident spectrum
- Tp.r Peak period of reflected spectrum
  - wm Complex weighting function for Fourier coefficient contribution from gage m
- wal Imaginary part of wa
- was Real part of wa
- w_n Complex weighting function for Fourier coefficient contribution from gage n
- wni Imaginary part of wn
- $w_{nR}$  Real part of  $w_n$ 
  - W Window function
  - x Horizontal cross-shore coordinate
- x_m Cross-shore coordinate of gage m
- x_n Cross-shore coordinate of gage n
- X Displacement or lag in x-direction
- $X_q$  Element of discrete Fourier transform at  $q^{th}$  frequency
- y Horizontal longshore coordinate
- yy Mnemonic for two-digit representation of year
- yymmdd Date mnemonic, a concatenation of year, month, and day mnemonics
  - ym Longshore coordinate of gage m
  - yn Longshore coordinate of gage n
  - Y Displacement or lag in y-direction
  - $\alpha$  Wave direction as fitted by maximum likelihood estimation
  - Δt Increment or step in time
  - As Increment of radian frequency
  - Δθ Increment of wave direction

- ε Initial wave phase
- $\epsilon_n$  Initial phase of nth component wave
- η Sea surface displacement
- $\eta_r$  Element of sea surface displacement time series at  $r^{\text{th}}$  time step
- λ Wavelength Lagrange multiplier
- Wave direction
- $\theta_m$  Element m of a discrete set of wave directions
- $\theta_n$  Direction of nth component wave
- Peak wave direction 

  Peak direction of incident wave spectrum

  From Shore 1
- $\theta_{p,i}$  Peak direction of incident wave spectrum  $f_{\mathcal{L}}$
- $\theta_{p,r}$  Peak direction of reflected wave spectrum
  - σ Radian wave frequency
  - $\sigma_n$  Radian frequency of  $n^{th}$  component wave
  - $\sigma_{\mathbf{q}}$  Element q of a set of discrete radian wave frequencies
  - $\chi$  Reflection coefficient based on wave heights
- $\chi_{\text{mo}}$  Reflection coefficient based on characteristic wave heights
- $\chi_{\rm p,i}$  Reflection coefficient at the peak frequency of the incident wave spectrum
- $\chi_{p,r}$  Reflection coefficient at the peak frequency of the reflected wave spectrum